

Development of Characterization and Simulation Methods for Carbon Fiber Sheet Molding Compounds



Leibniz-Institut für
Verbundwerkstoffe

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Steiner

The 15th International Conference on Flow Processes in Composite Materials, June 27-29, 2023 West Lafayette, IN, USA

- Introduction & Motivation
- Material and Process Characterization
 - Fiber orientation: Semi-finished product
 - Flow/filling characterization
 - Fiber orientation: Pressed specimens
- Process Simulation
 - Material model
 - Application
- Conclusions

Introduction

Motivation

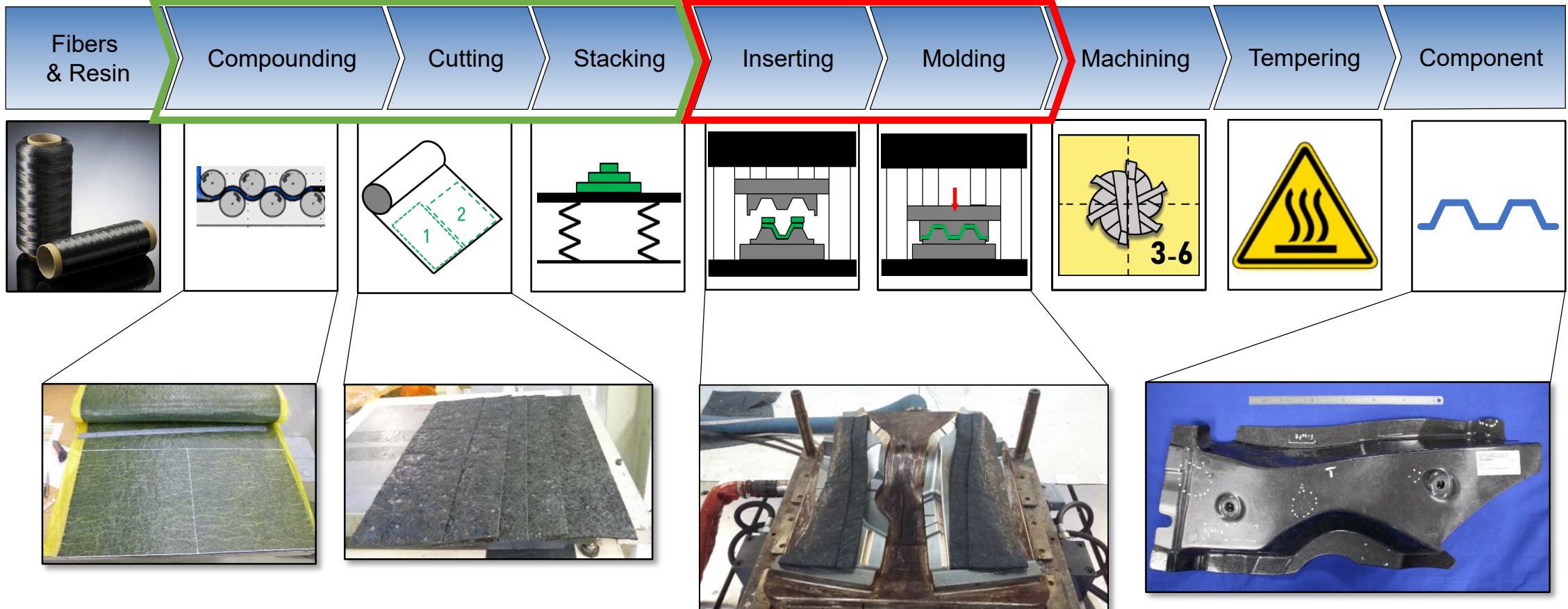
Material & Process
Characterization

Process Simulation

Conclusions

Production of SMC-Prepreg

Process Simulation



Romanenko V, Duhovic M, et al. Advanced process simulation of compression molded carbon fiber sheet molding compound (C-SMC) parts in automotive series applications. Compos Part A Appl Sci Manuf 2022;157:106924. <https://doi.org/10.1016/j.compositesa.2022.106924>.

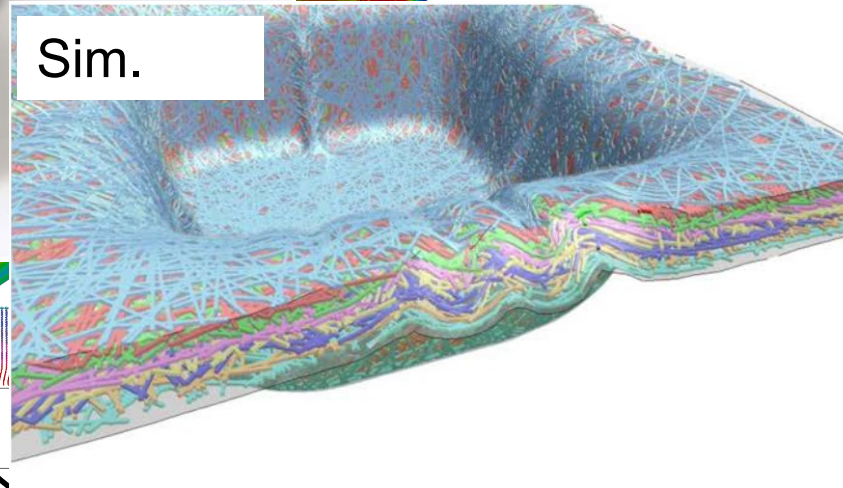
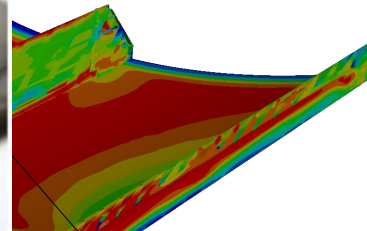
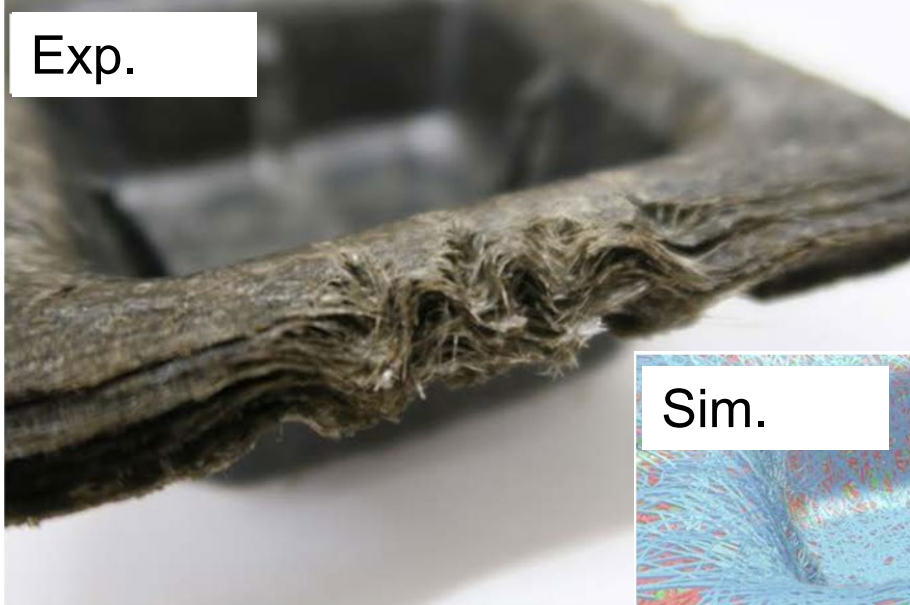
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Goal: Prediction of fiber orientation

- ➔ Flow/filling behavior
- ➔ Manufacturing defects/failure behavior
- ➔ Warpage
- ➔ Structural behavior

Solutions:

- ➔ Continuum mechanics material models
- ➔ Direct fiber simulation

Similarities:

- ➔ Initial fiber orientation influences process simulation result!

Hayashi S, Chen H, Hu W. Development of New Simulation Technology for Compression Molding of Long Fiber Reinforced Plastics using LS-DYNA®. 15th International LS-DYNA® Users Conference <https://www.dynalook.com/conferences/15th-international-ls-dyna-conference/composites/development-of-new-simulation-technology-for-compression-molding-of-long-fiber-reinforced-plastics-using-ls-dyna-r>

Introduction

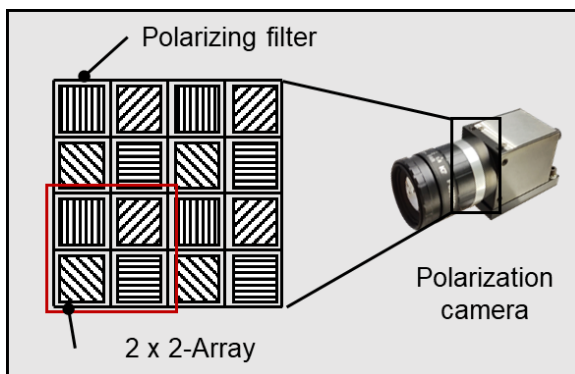
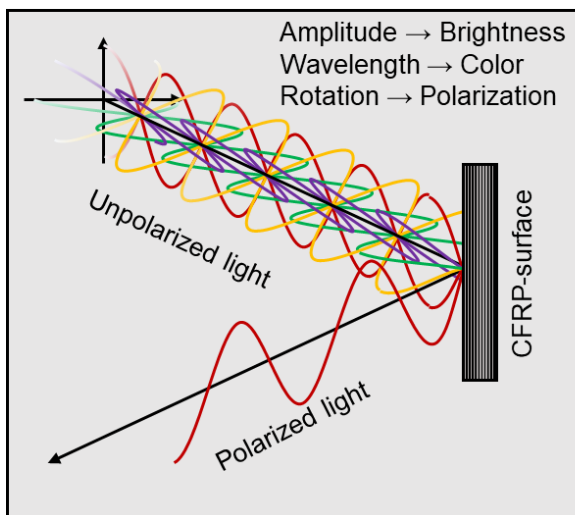
Motivation

Material & Process
Characterization

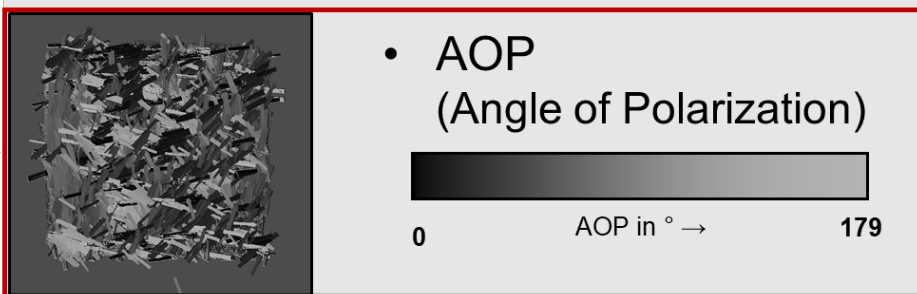
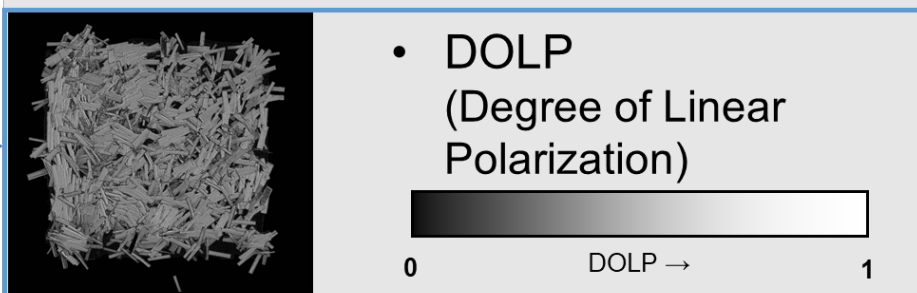
Process Simulation

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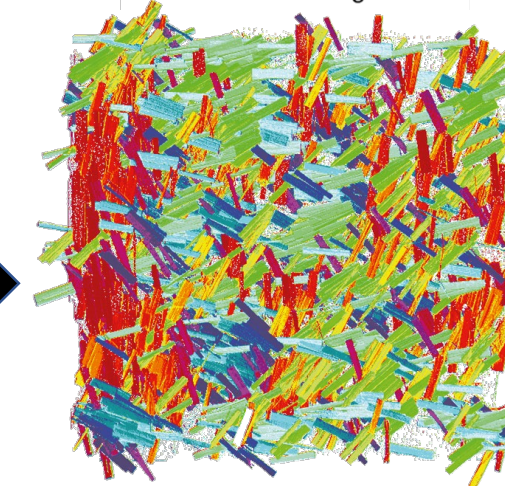
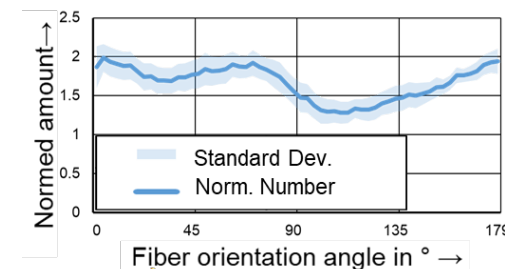
Carbon fibers polarize ambient light!



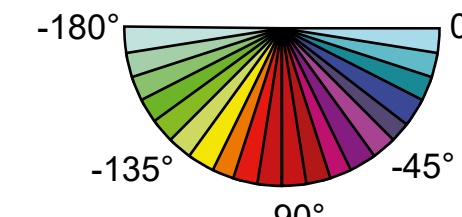
Complex example: random chopped fibers



Components



Fiber Orientation Angle



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Introduction

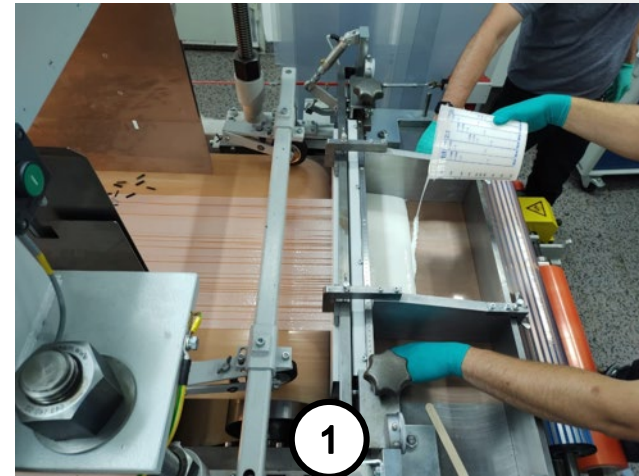
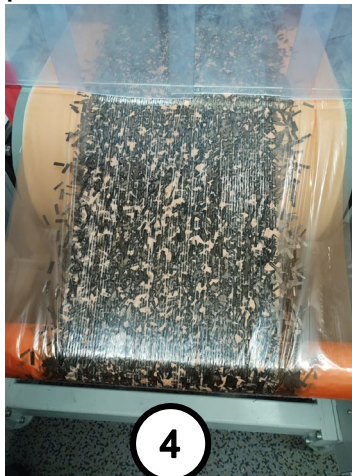
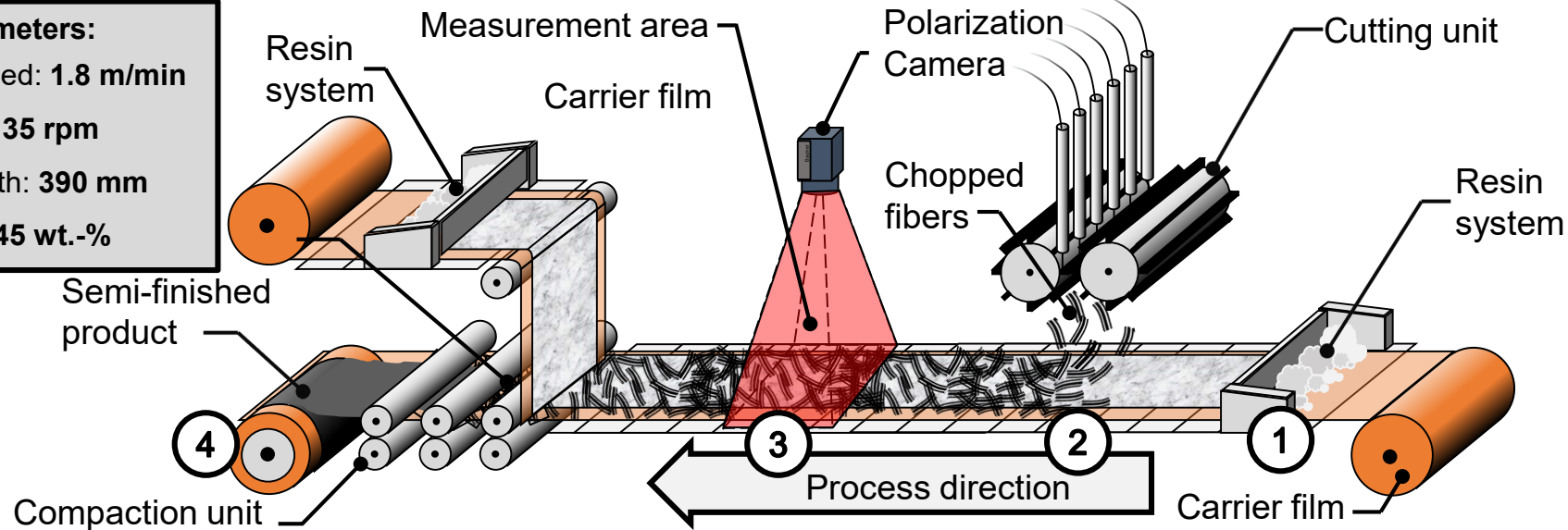
Motivation

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Process parameters:
Production speed: 1.8 m/min
Cutting speed: 35 rpm
Production width: 390 mm
Fiber content: 45 wt.-%



Introduction

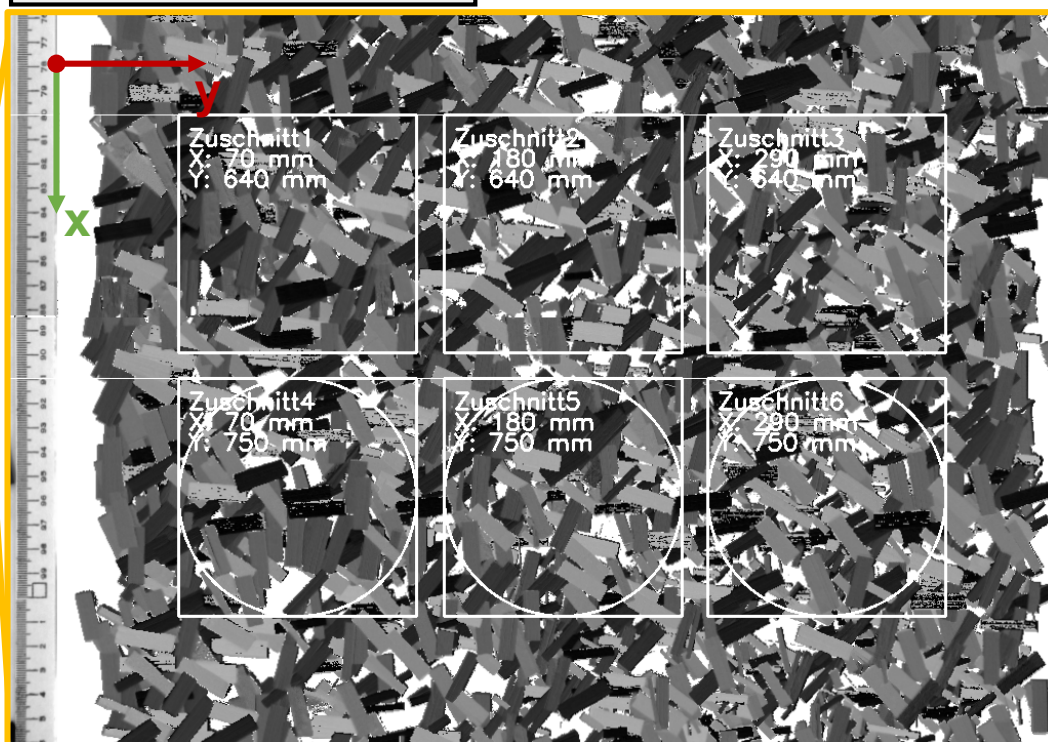
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**Material & Process
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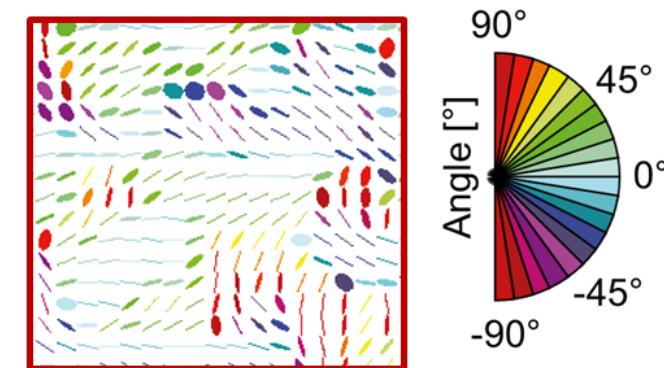
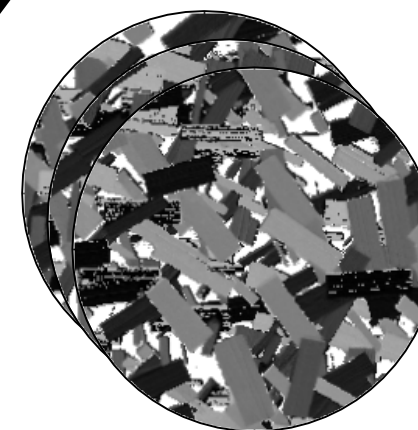
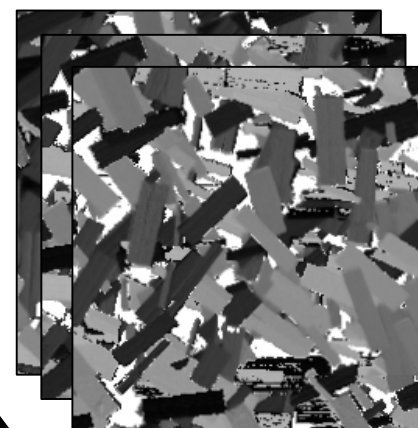
Process Simulation

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Cutting plan



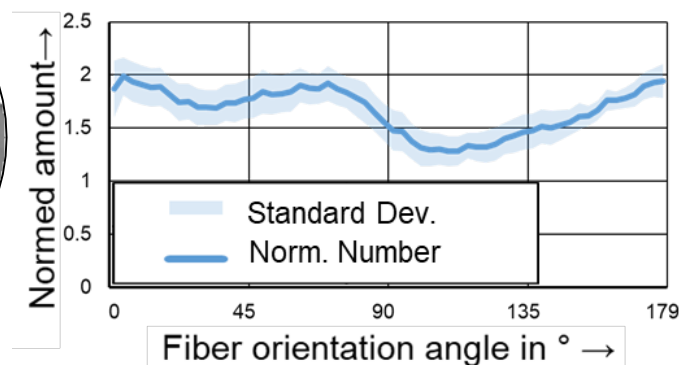
Digital cut-outs



Fiber Orientation Tensors as .csv



Fiber Orientation Angles as .csv



Digital semi-finished product

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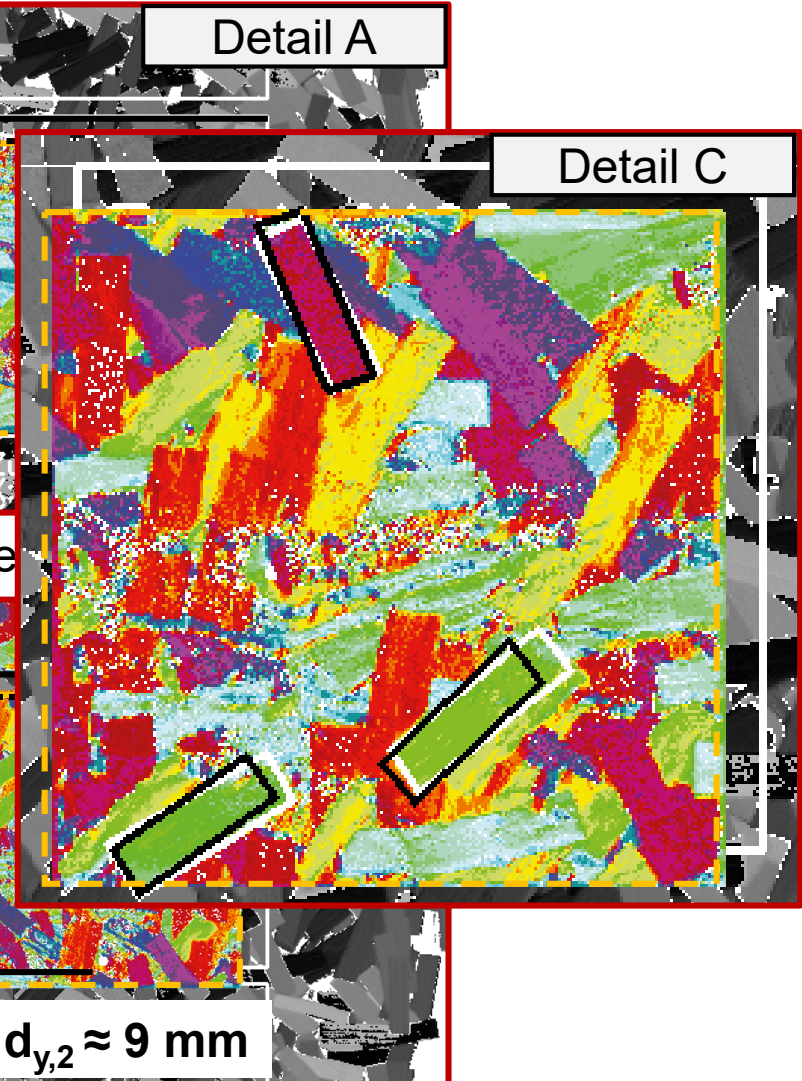
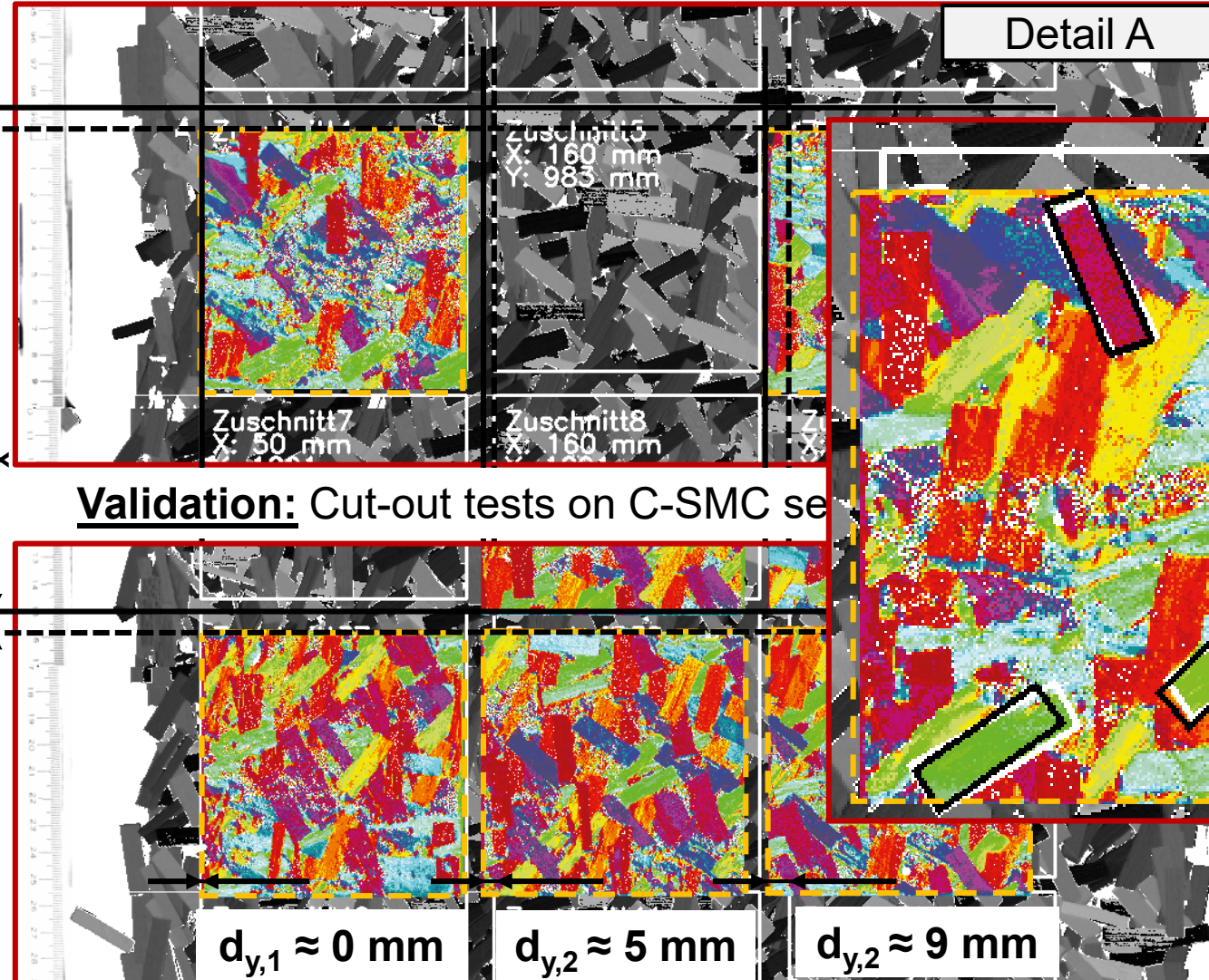
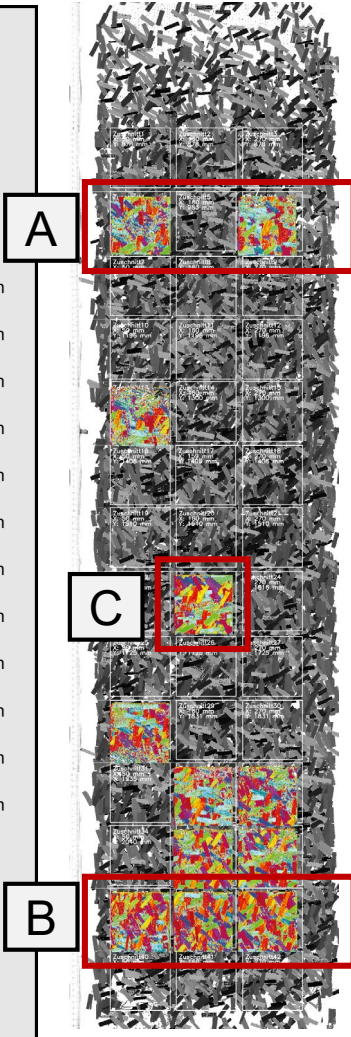
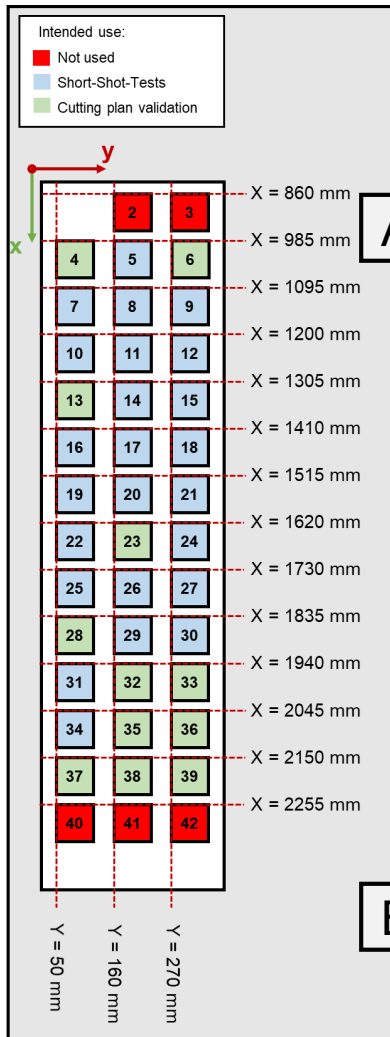
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Validation: Cut-out tests on C-SMC se

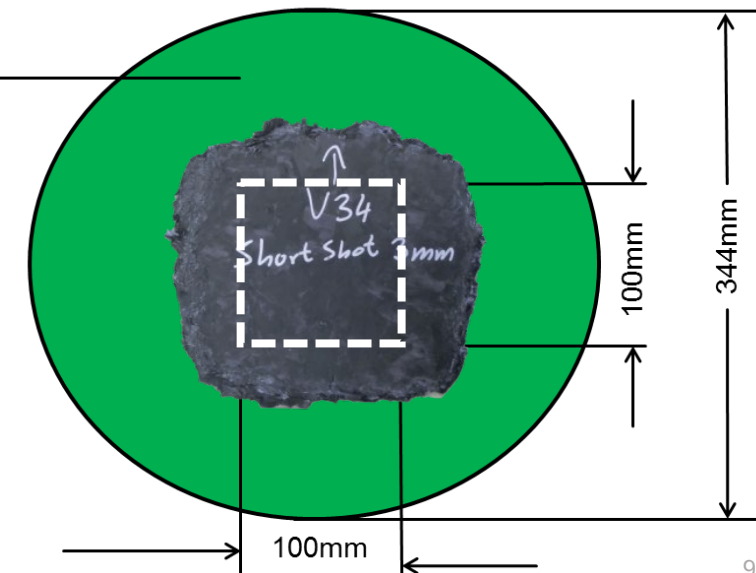
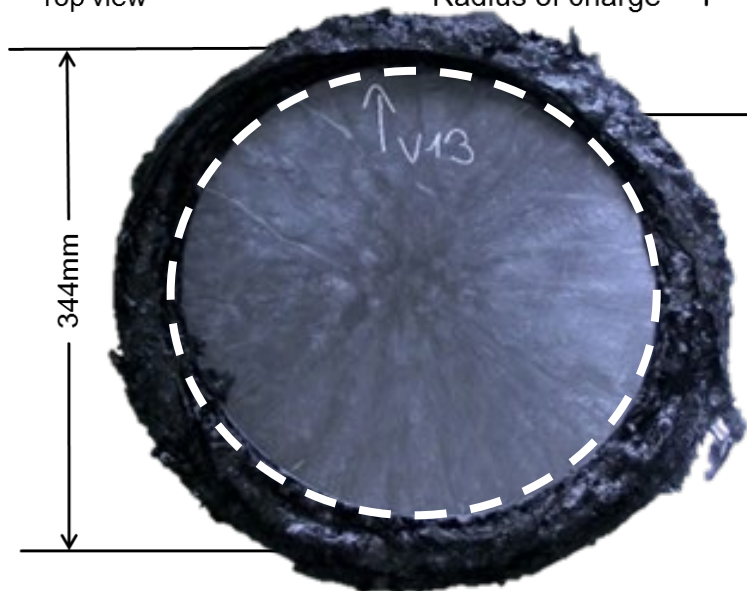
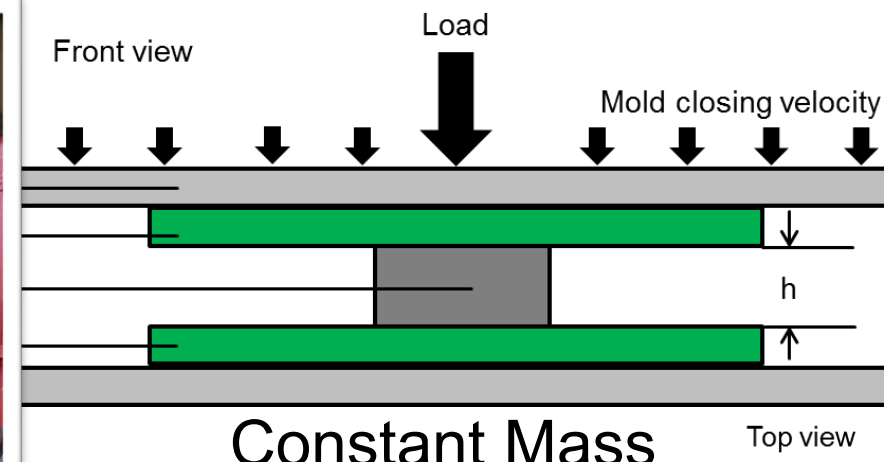
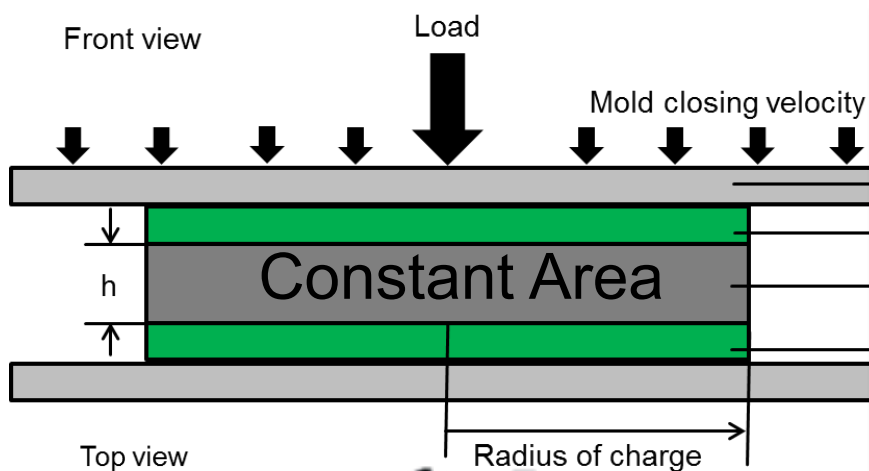
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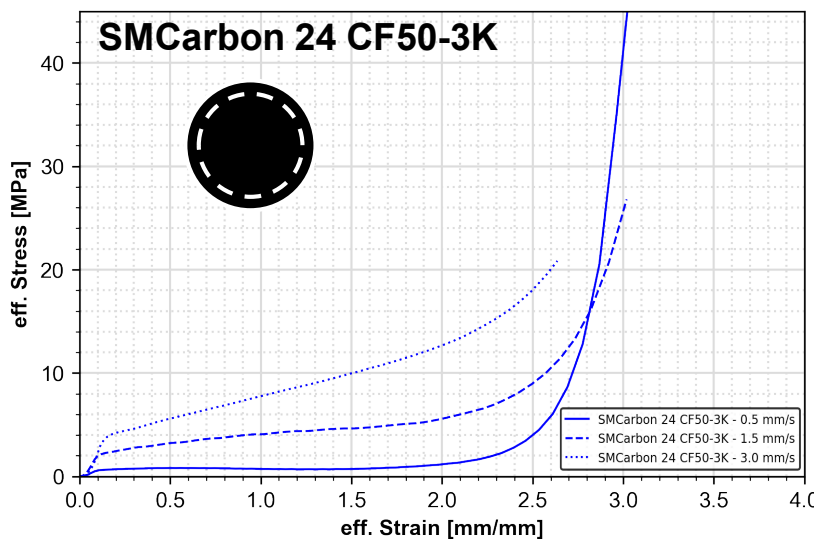
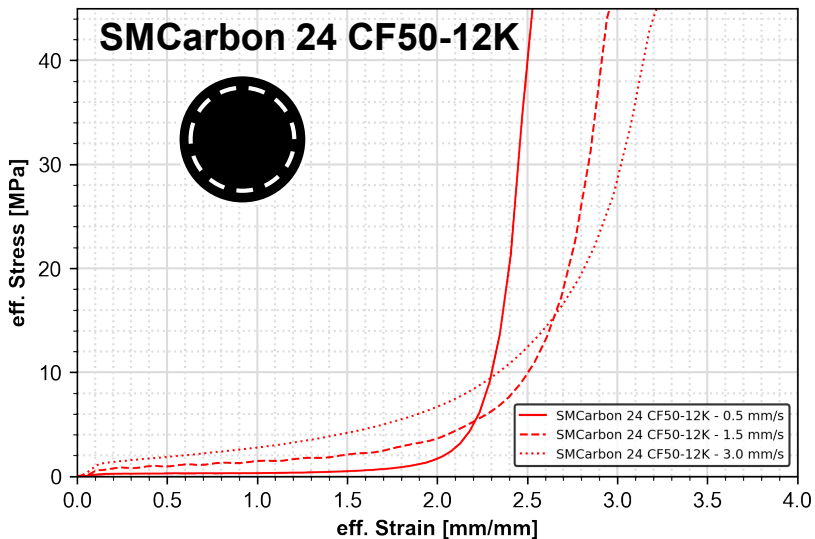
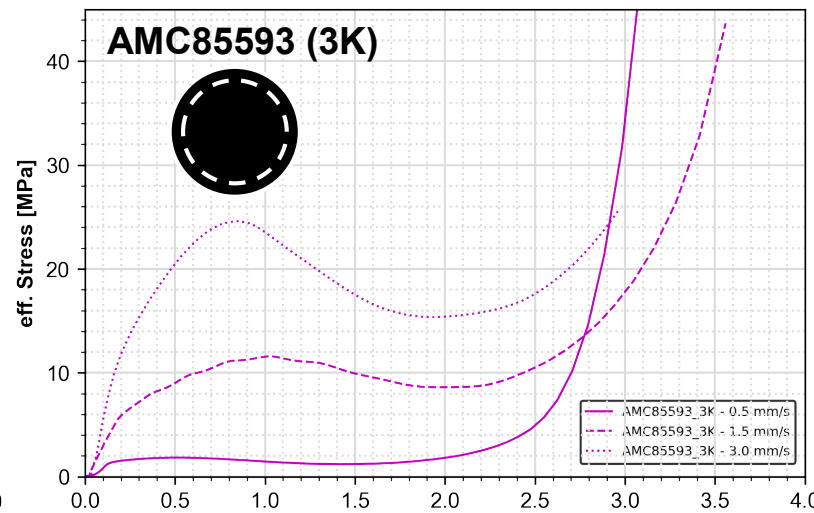
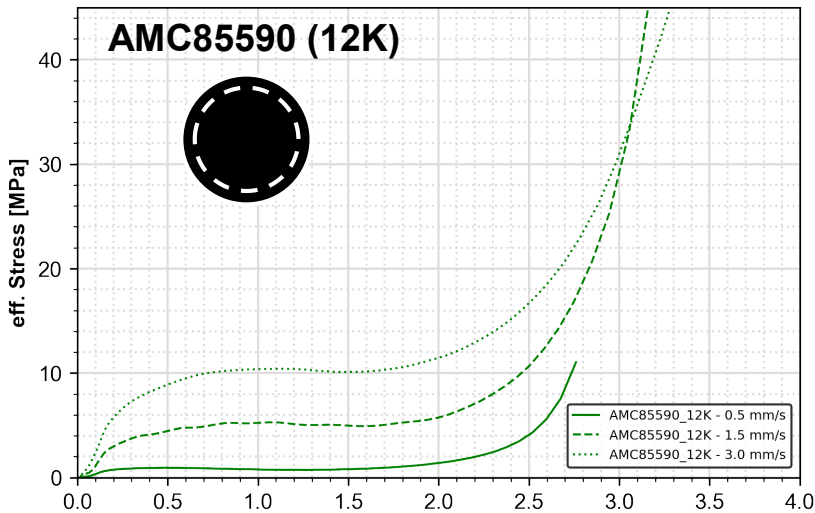
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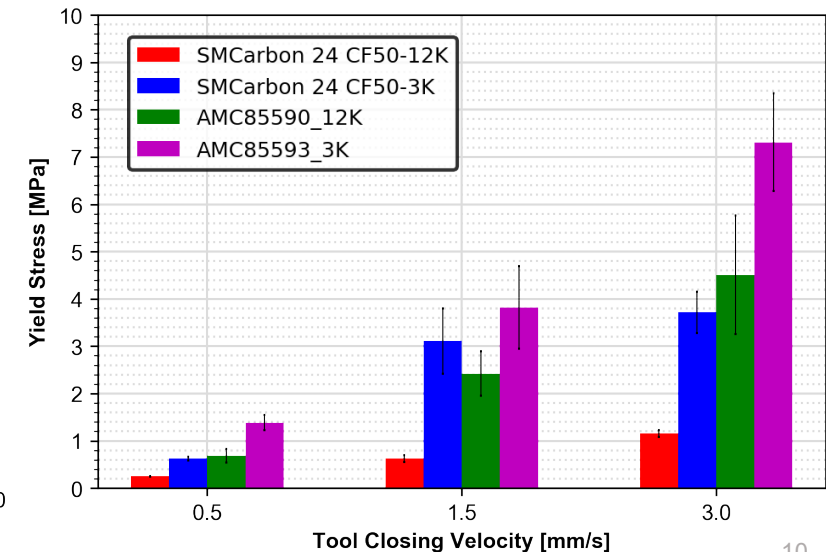


Differences:

- Two manufacturers (Quantum, Polynt)
- 12K und 3K filaments

Similarities:

- Vinylester based
- Fiber content approx. 50 wt%
- Fiber length: 1 inch



Introduction

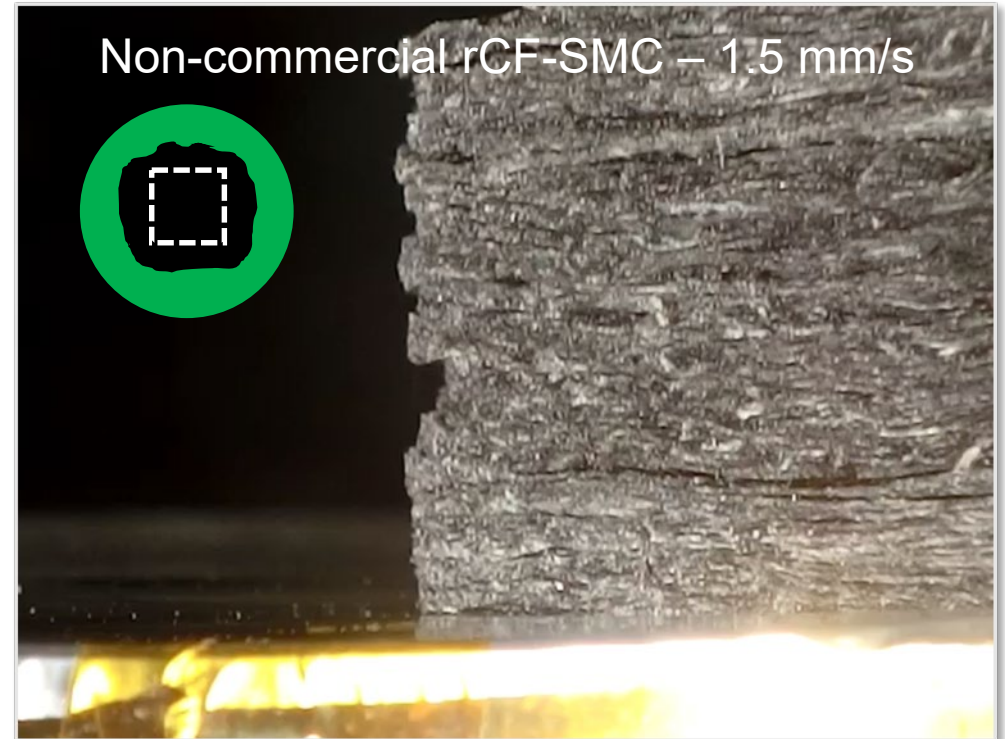
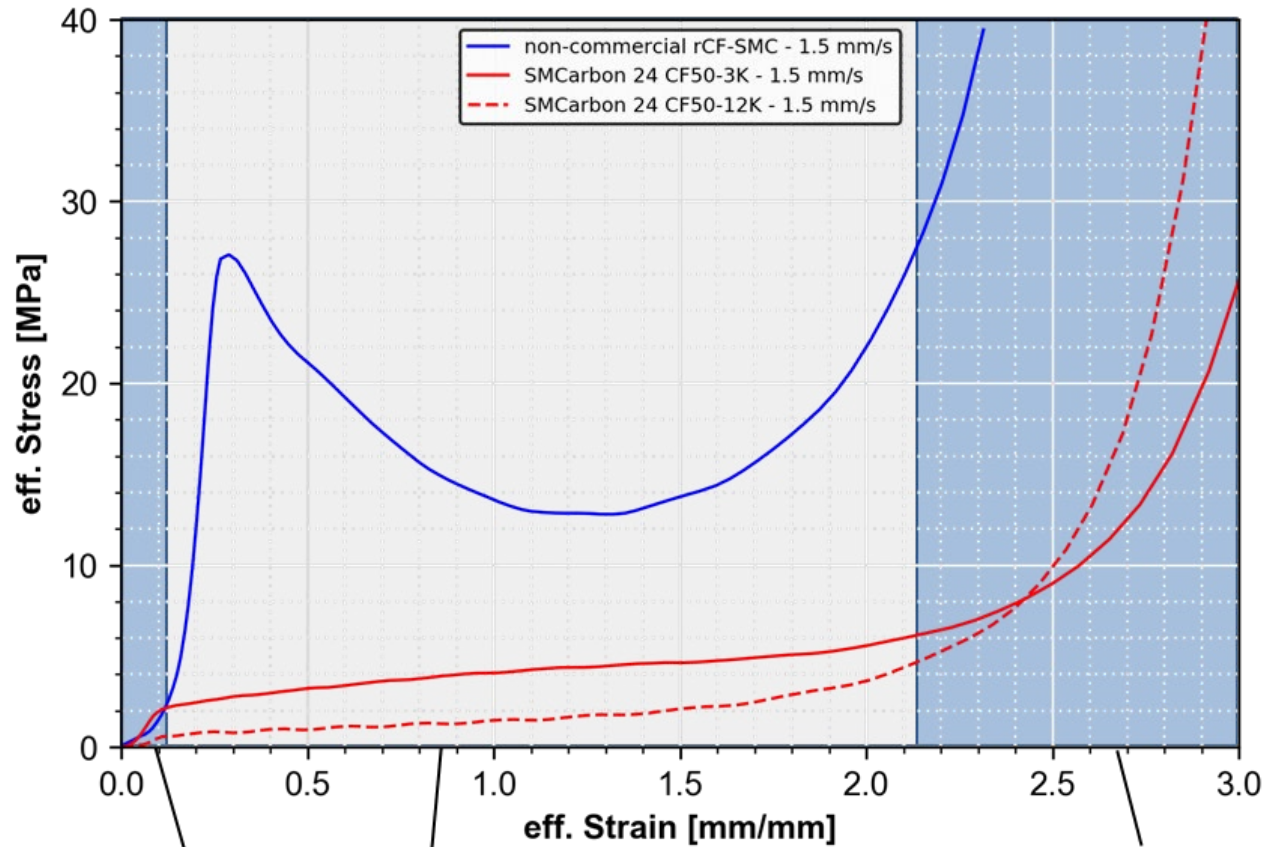
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Typical C-SMC material shows a compaction phase follows by a flow phase during compression molding



Compaction

Plastic
Flow

Plastic Flow +
Compaction +
Friction

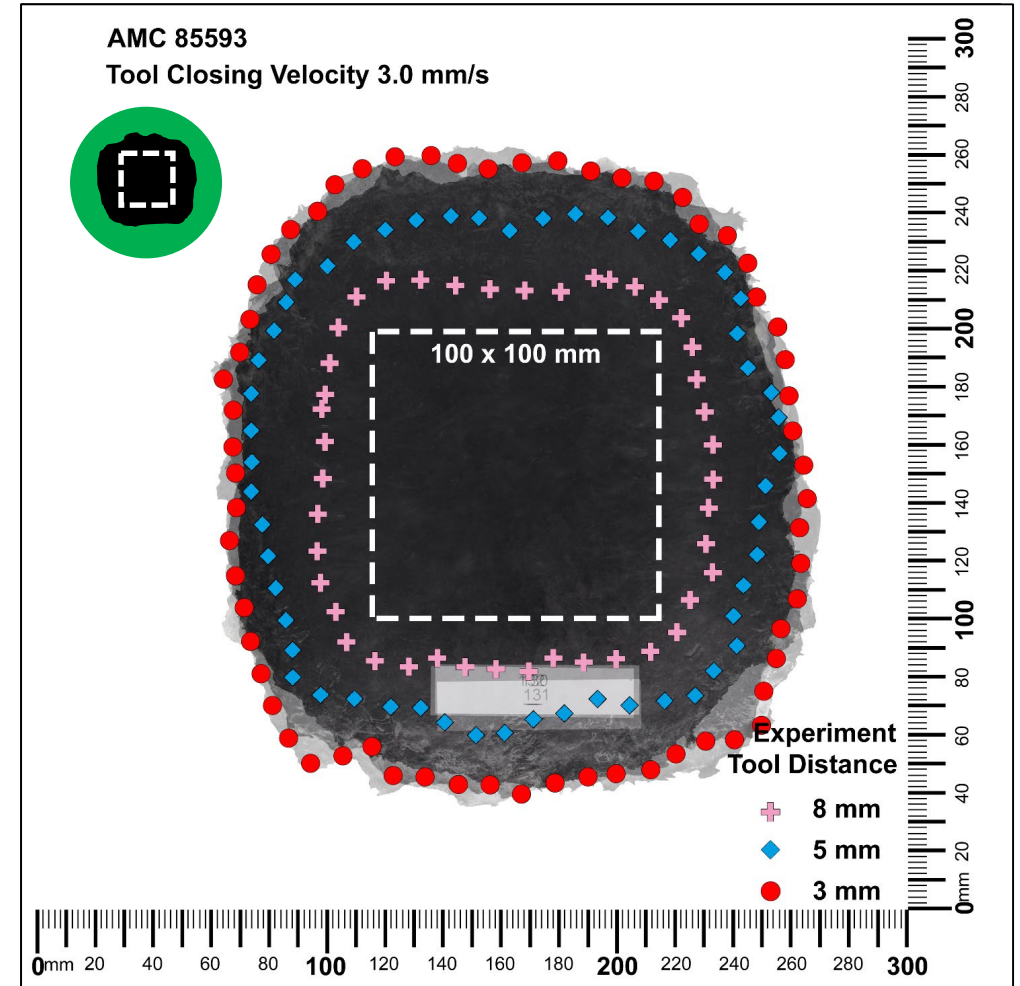
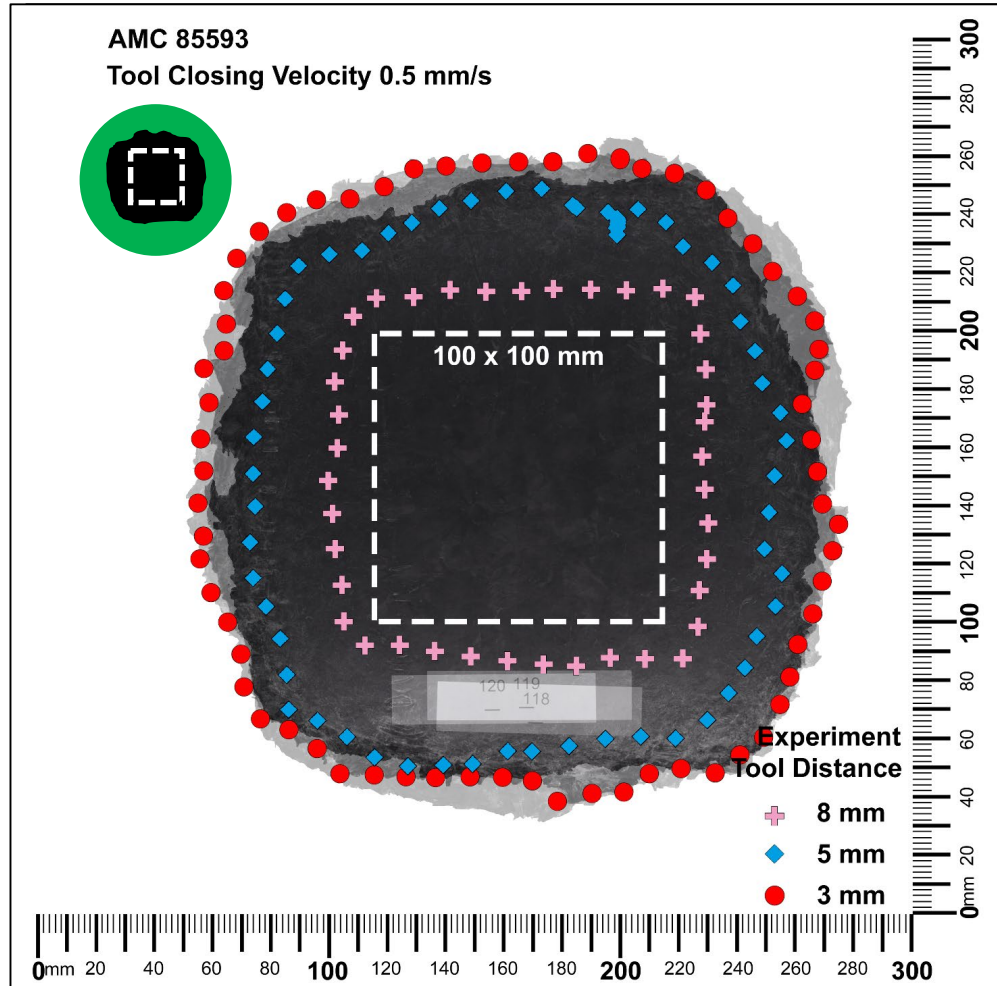
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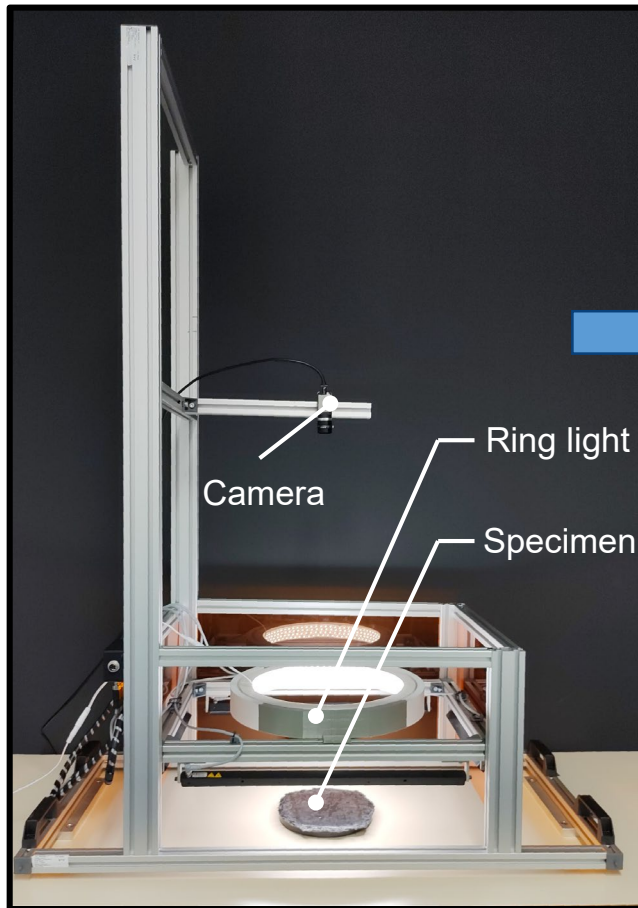
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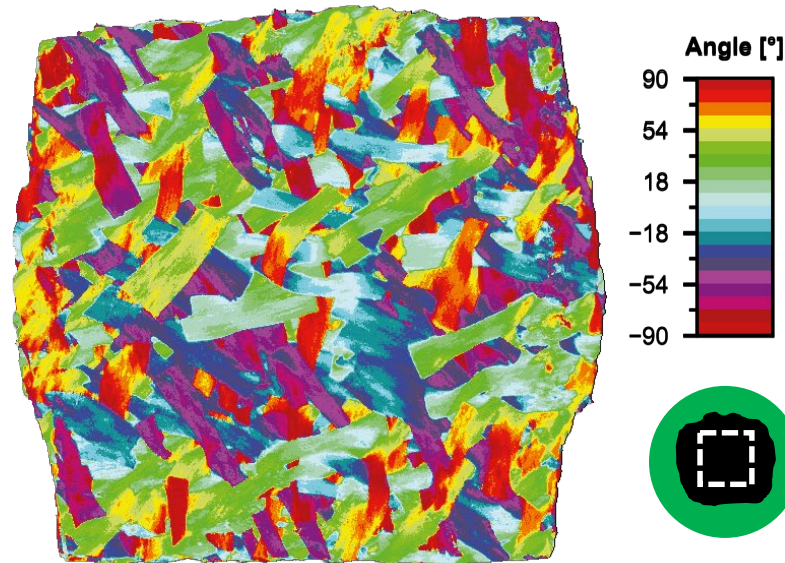
Conclusions

Optical measurement of surface fiber orientation



Polarization image data

→ Greyscale shows fiber orientation angle in range from -90° to 90° to picture horizontal



→ Colored for better visibility

Introduction

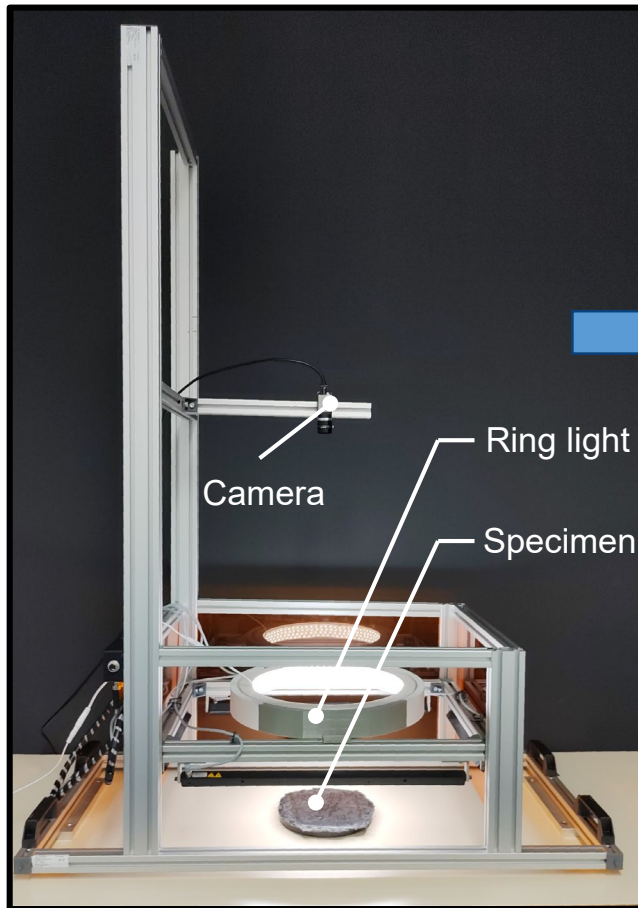
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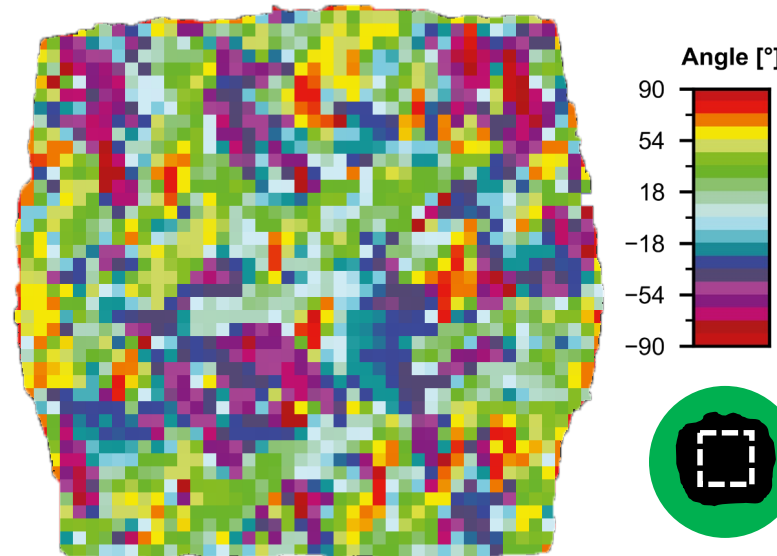
Process Simulation

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Optical measurement of surface fiber orientation



→ Place grid over specimen for reducing
data and comparison with simulation



→ Grid resolution corresponds to
element size in later simulation

Introduction

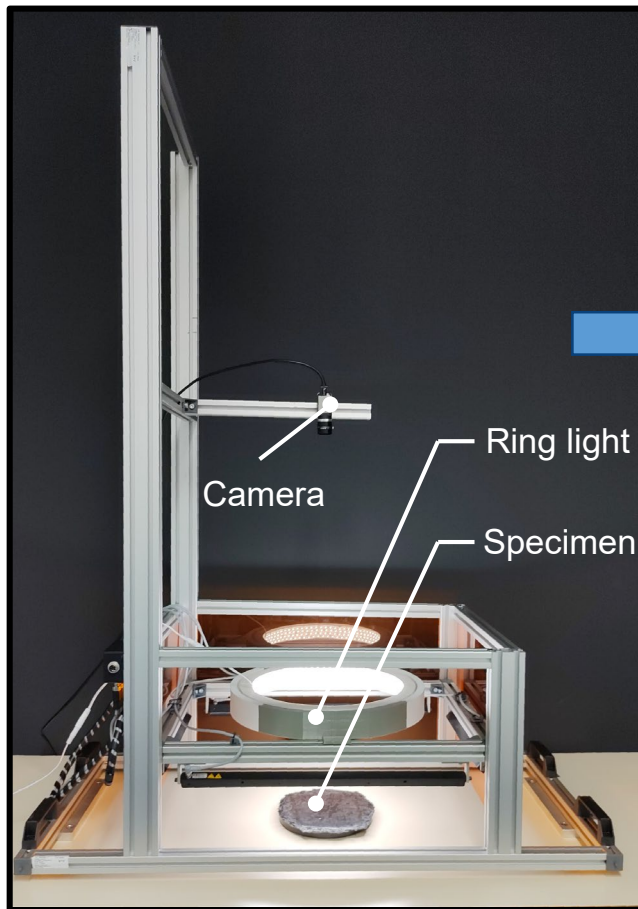
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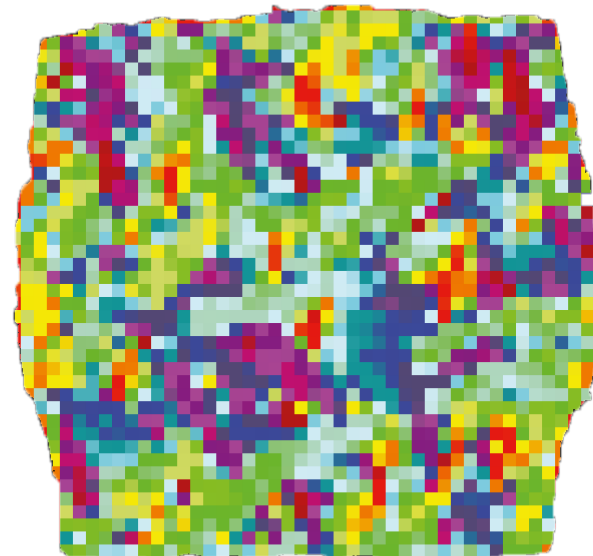
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Optical measurement of surface fiber orientation



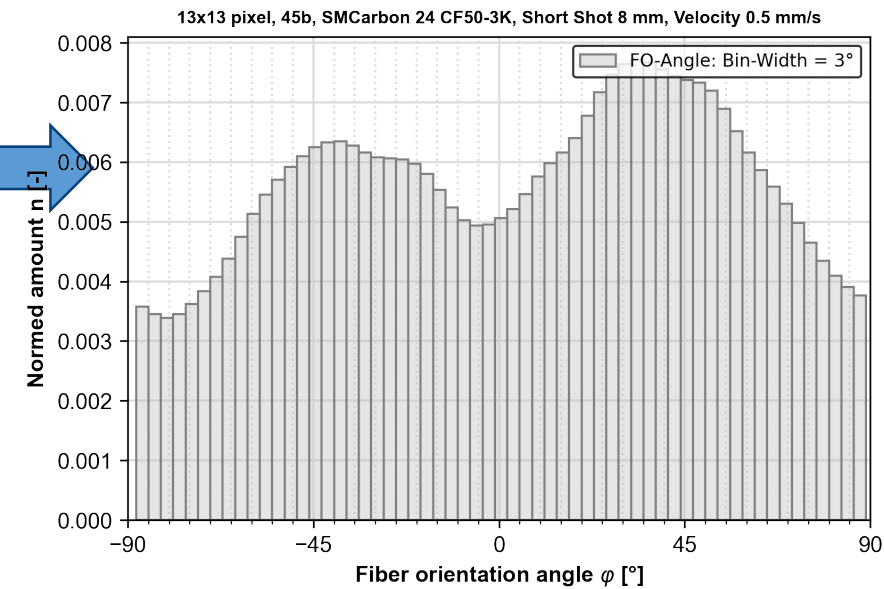
→ Place grid over specimen for reducing data and comparison with simulation



→ Grid resolution corresponds to element size in later simulation

Analysis

→ FO is visualized as histogram with Gaussian fit



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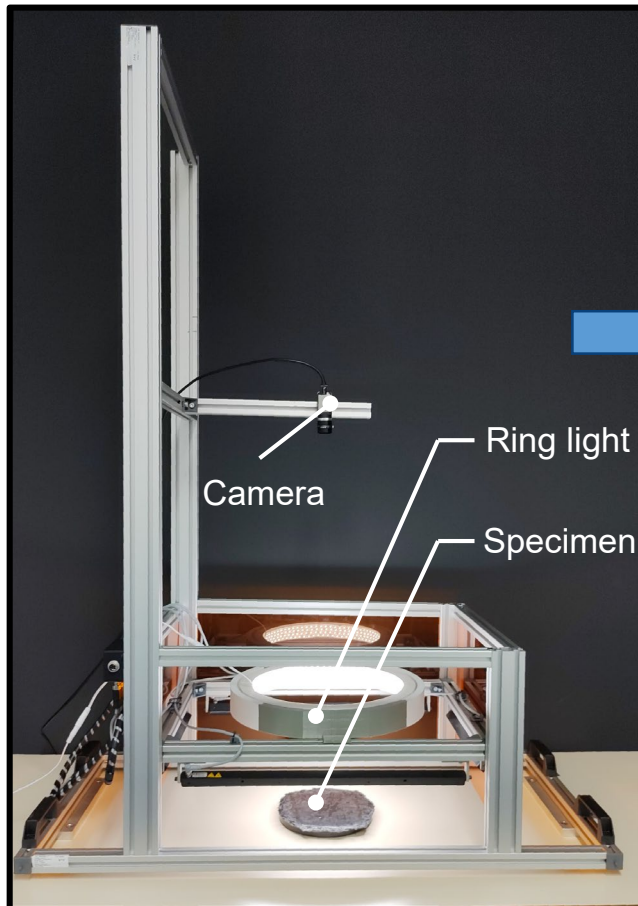
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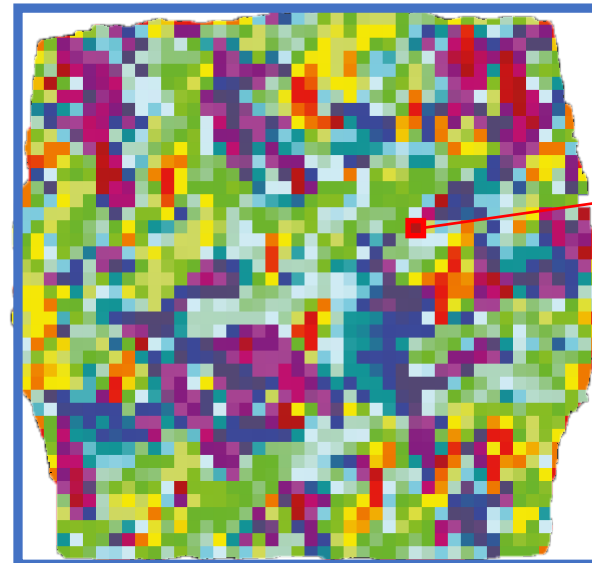
Conclusions

Optical measurement of surface fiber orientation



Polarization image data

→ Calculation of fiber orientation tensor for each grid cell



Analysis

python

→ FOT information for each grid cell, for example

0.685	0.465	0.000
	0.315	0.000
		0.000

→ Average FOT for specimen

0.456	-0.043	0.000
	0.544	0.000
		0.000

→ An in-plane fiber orientation is assumed
→ All z-components of FOT are zero

Introduction

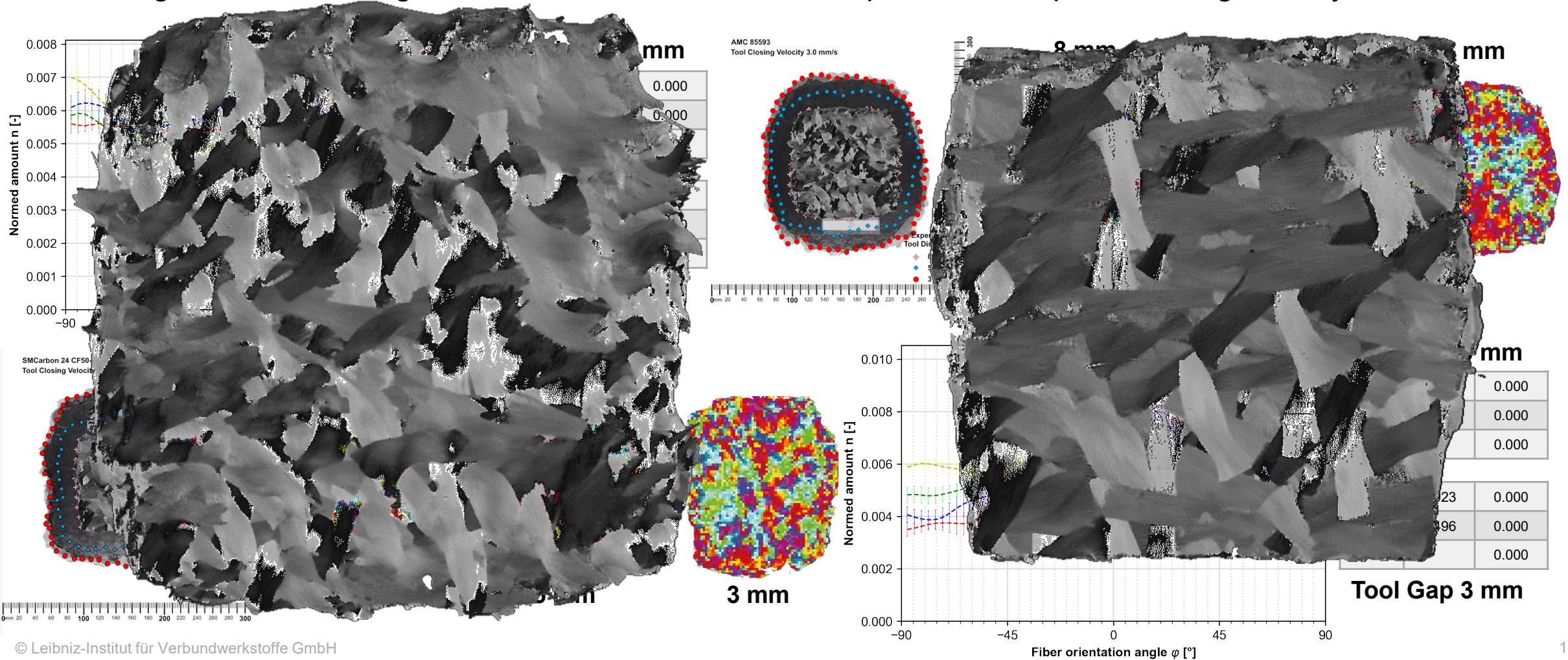
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Histograms and average FOT information of short shot specimens for press closing velocity of 3.0 mm/s



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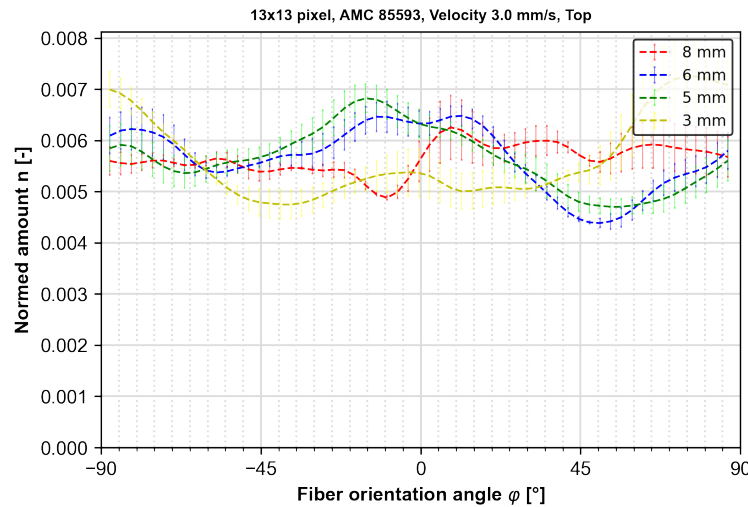
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Histograms and average FOT information of short shot specimens for press closing velocity of 3.0 mm/s

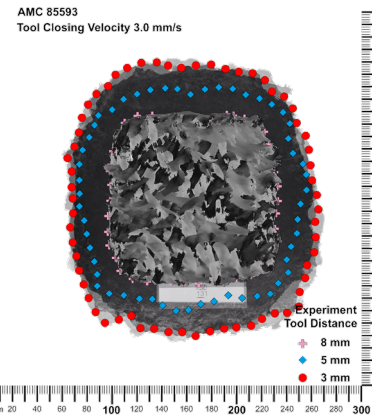


Tool Gap 8 mm

0.498	-0.012	0.000
	0.502	0.000
		0.000

0.458	-0.014	0.000
	0.542	0.000
		0.000

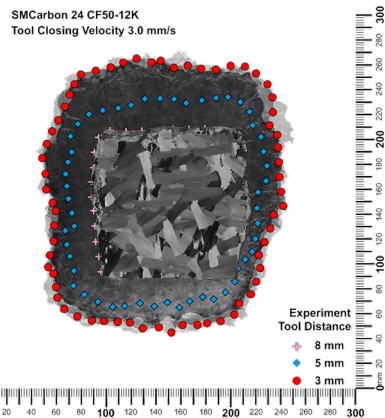
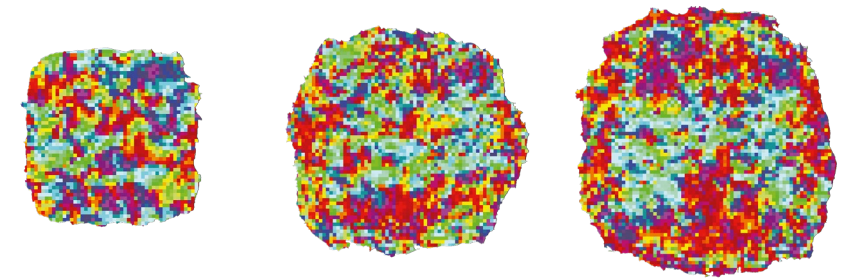
Tool Gap 3 mm



8 mm

5 mm

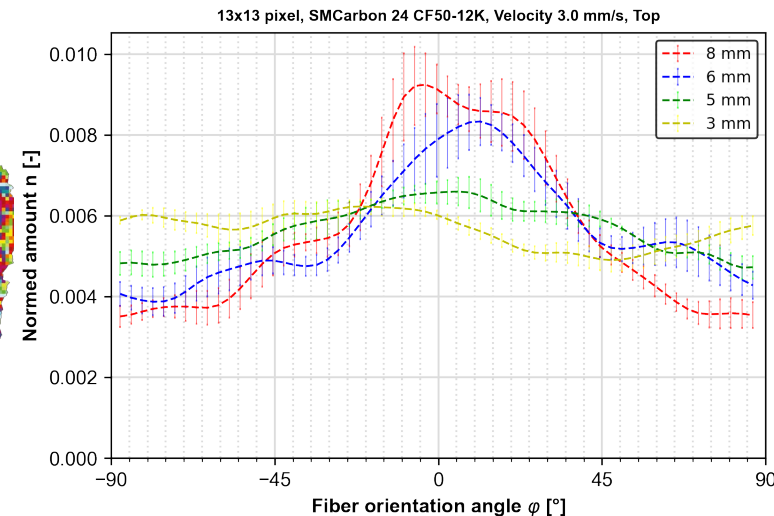
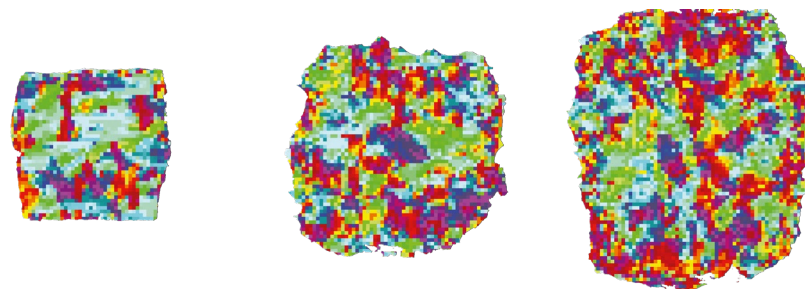
3 mm



8 mm

5 mm

3 mm



Tool Gap 8 mm

0.621	-0.021	0.000
	0.379	0.000
		0.000

0.504	0.023	0.000
	0.496	0.000
		0.000

Tool Gap 3 mm

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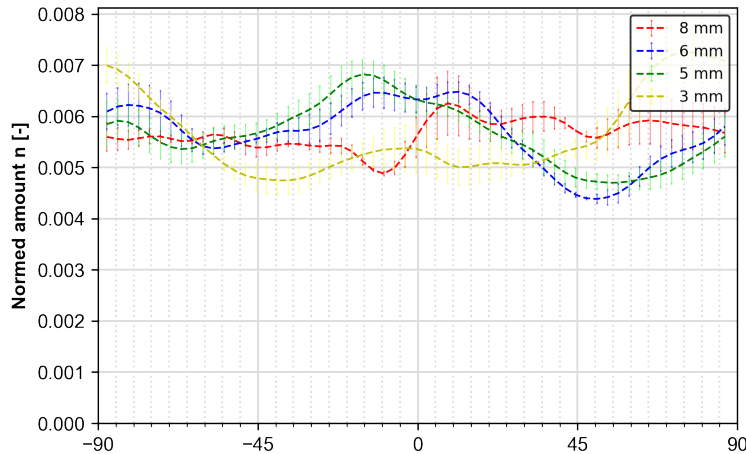
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Histograms and average FOT information of short shot specimens for press closing velocity of 3.0 mm/s

13x13 pixel, AMC 85593, Velocity 3.0 mm/s, Top



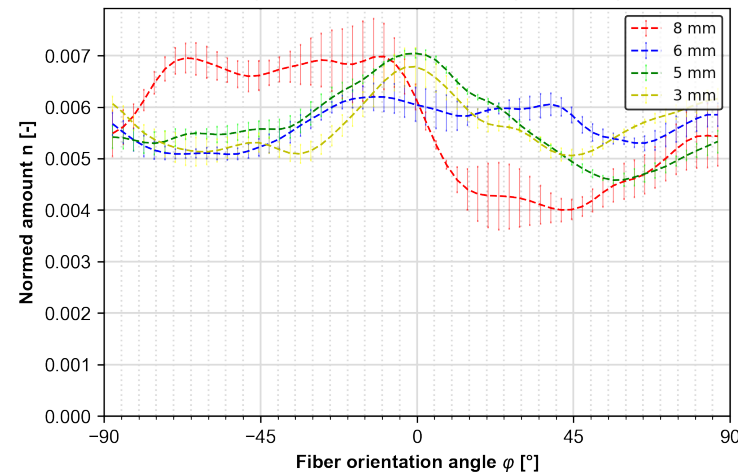
Tool Gap 8 mm

0.498	-0.012	0.000
	0.502	0.000
		0.000

0.458	-0.014	0.000
	0.542	0.000
		0.000

Tool Gap 3 mm

13x13 pixel, SMCarbon 24 CF50-3K, Velocity 3.0 mm/s, Top



Tool Gap 8 mm

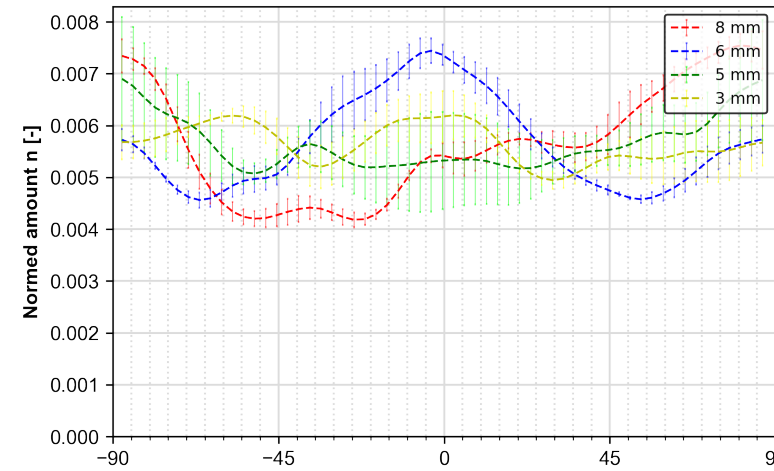
0.502	0.067	0.000
	0.498	0.000
		0.000

0.510	-0.005	0.000
	0.490	0.000
		0.000

Tool Gap 3 mm

Fiber orientation angle φ [°]

13x13 pixel, AMC 85590, Velocity 3.0 mm/s, Top



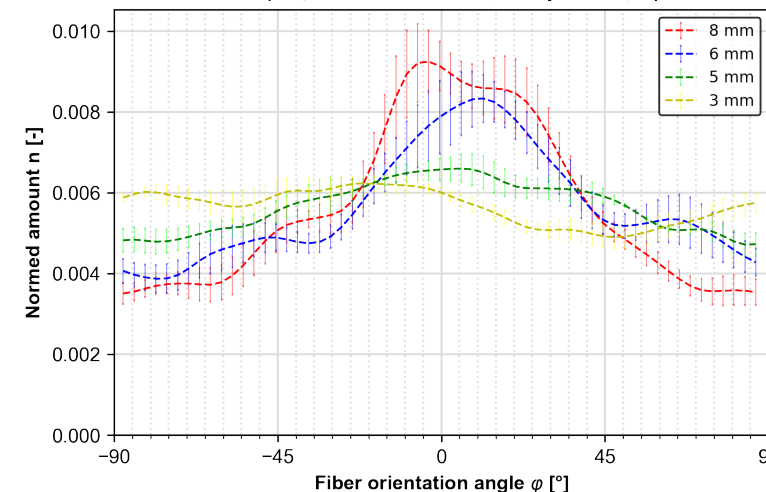
Tool Gap 8 mm

0.456	-0.043	0.000
	0.544	0.000
		0.000

0.501	0.012	0.000
	0.499	0.000
		0.000

Tool Gap 3 mm

13x13 pixel, SMCarbon 24 CF50-12K, Velocity 3.0 mm/s, Top



Tool Gap 8 mm

0.621	-0.021	0.000
	0.379	0.000
		0.000

0.504	0.023	0.000
	0.496	0.000
		0.000

Tool Gap 3 mm

Fiber orientation angle φ [°]

Introduction

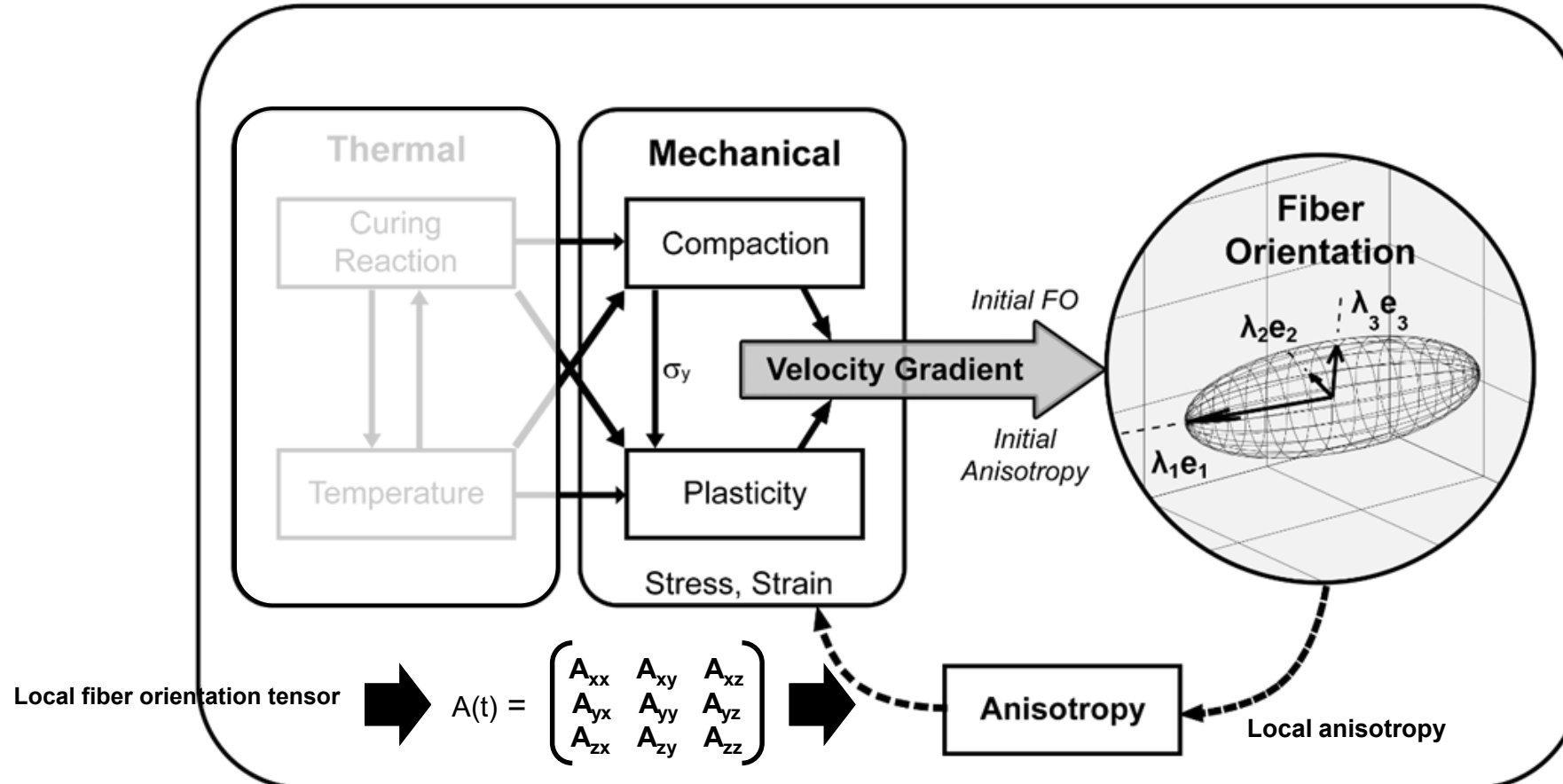
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Development of a material model that takes into account the basic effects, uses mathematical formulations that are as simple as possible and is built upon a modular principle, whereby each block represents specific aspect of material behavior.



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Arbitrary-Lagrangian-Eulerian (ALE) – Suitable for the representation of bodies that combine the properties of fluids and solids.

Calculation in two steps:

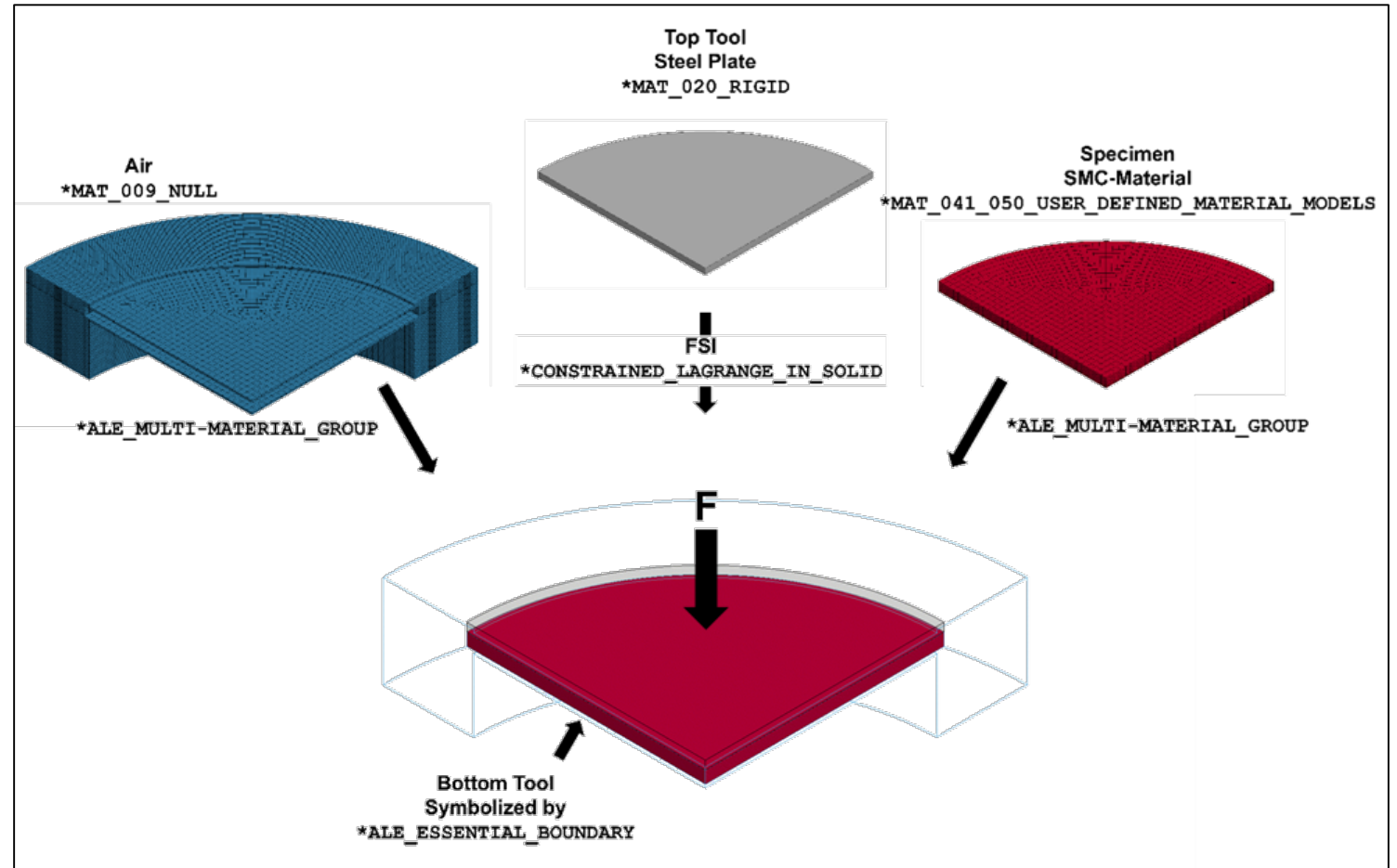
1. Lagrangian step:

Calculation of deformation in a Lagrangian formulation

2. Advection step:

Remapping of element state variables back onto the reference mesh.

Main difference to Eulerian method:
ALE allows a movement and
deformation of reference mesh.



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Folgar-Tucker-Equation

Based on the equation by Jeffery (1922):

$$\frac{D}{Dt} p = \hat{M}^T \cdot p - (p^T \cdot \hat{M} \cdot p) p$$

p	=	Orientation vector
\hat{M}	=	Effective local velocity gradient

Orientation of an ellipsoid particle in an infinite Newtonian fluid

$$\frac{DA}{Dt} = (W \cdot A - A \cdot W) + \xi (D \cdot A + A \cdot D - 2A : D) + 2C_i \dot{\gamma} (I - 3A)$$

Folgar-Tucker-Equation (1984) Developed for injection molding

A	=	Fiberorientation Tensor 2. Order $A = \langle pp \rangle$
\mathbb{A}	=	Fiberorientation Tensor 4. Order
W	=	Vorticity Tensor 2. Order

D	=	Deformation Tensor 2. Order
ξ	=	Geometry Factor 2. Order
I	=	Unit Tensor 2. Order

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Folgar-Tucker-Model + Maier-Saupe term

$$\frac{DA}{Dt} = \mathbf{M}\mathbf{A} + \mathbf{M}^T\mathbf{A} - 2\mathbf{A}:\mathbf{M} - 6C_i\dot{\gamma} \left(\mathbf{A} - \frac{1}{3}\mathbf{I} \right)$$

$$\mathbf{M} = \lambda\boldsymbol{\gamma} + \frac{1}{2}(\nabla\mathbf{u} - \nabla\mathbf{u}^T) + \dot{\gamma}U_0\mathbf{A}$$

$$\lambda = \frac{r_a^2 - 1}{r_a^2 + 1}$$

$$\dot{\gamma} = \sqrt{\frac{1}{2}\boldsymbol{\gamma}:\boldsymbol{\gamma}}$$

$$\boldsymbol{\gamma} = \frac{1}{2}(\nabla\mathbf{u} + \nabla\mathbf{u}^T)$$



A	=	Fiber orientation tensor 2. order $\mathbf{A} = \langle pp \rangle$
A	=	Fiber orientation tensor 4. order
M	=	Maier-Saupe term
$\nabla\mathbf{u}$	=	Velocity gradient
U_0	=	Maier-Saupe potential
I	=	Unity tensor 2. order
r_a	=	Fiber Geometry factor

Latz, A.; Strautins, U.; Niedziela, D.: Comparative numerical study of two concentrated fiber suspension models. J. Non-Newtonian Fluid Mech. 165, pp. 764-781 (2010).

Material card for user-defined material model implemented in LS-DYNA.

Keyword Input Form

NewID MatDB RefBy Pick Add Accept Delete Default Done

Use *Parameter Comment (Subsys: 7 Materialmodel_Polynt_12K_vf.k) Setting

*MAT_USER_DEFINED_MATERIAL_MODELS_(TITLE) (041_050) (1)

TITLE
Umat Elastic-plastic Fiber Orientation

1	MID	RO	MT	LMC	NHV	IORTHO	IBULK	IG
	3	2400.0000	41	32	42	0	4	3

2	IVECT	IFAIL	ITHERM	IHYPER	IEOS	LMCA	UNUSED	UNUSED
	0	0	0	-2	0	0	0	0

Repeated Data by Button and List

3	P1	P2	P3	P4	P5	P6	P7	P8
	3.000000E8	0	100000000	6.667000E7	0.0	0.5	0.5	0

1	2	3	4	5	6	7	8	9	10	11	12
1	3.000000E8	0	100000000	6.667000E7	0.0	0.5	0.5	0			
2	0	0	0.025	0.01	1.0005	250400.0					
3	100000.0	9	10	1115315	1	7	8	0			
4	11	0	0	0	0	0	0	0			

Data Pt. 1

Replace Insert

Delete Help

Repeated Data by Button and List

Total Card: 1 Smallest ID: 3 Largest ID: 3 Total deleted card: 0

RO: Combined density of matrix and fibers

MT: User Material ID

LMC: No. of material constants to be defined

NHV: No. of history variables constants to be output

P1-P8: The first 8 (of 26) user defined material parameters

Cm(1)-Cm(26): Tensile modulus, Poisson's ratio, shear modulus, compression modulus, A_{xx} , A_{yy} , A_{zz} , A_{zy} , A_{xz} , A_{zy} , fiber length, fiber diameter, Maier-Saupe Potential, fiber interaction coefficient...etc.

Introduction

Motivation

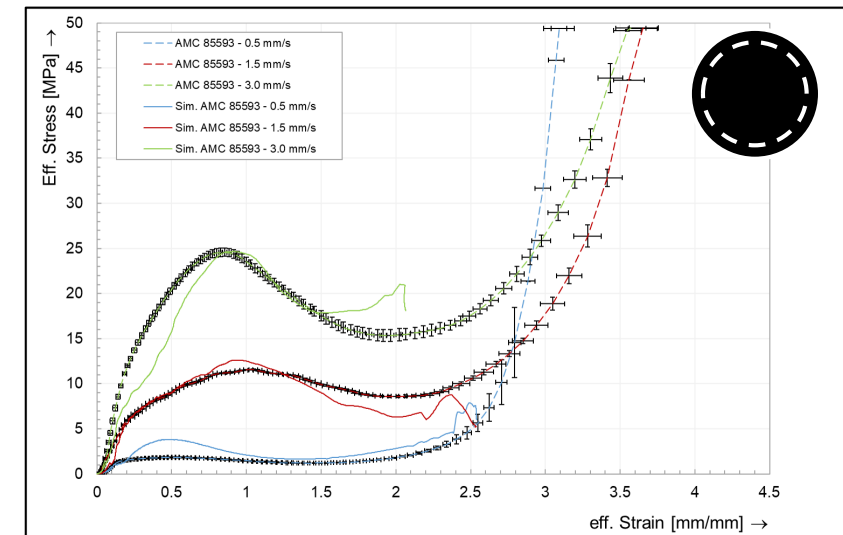
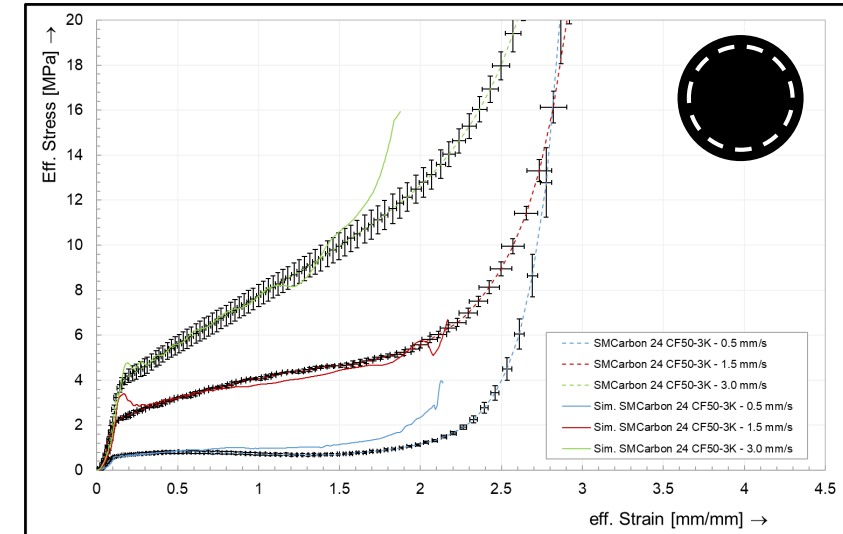
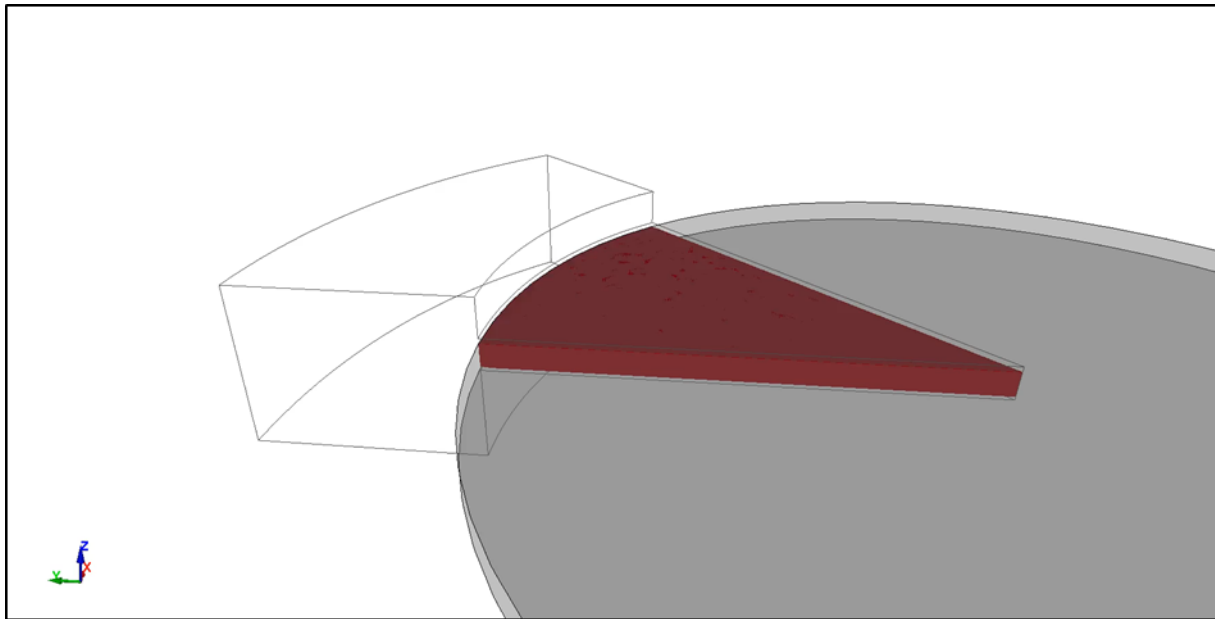
Material & Process
Characterization

Process Simulation

Conclusions

Validation and evaluation of the accuracy of the material model carried out via post-simulation of the characterization tests.

Material model calibration



Introduction

Motivation

Material & Process
Characterization

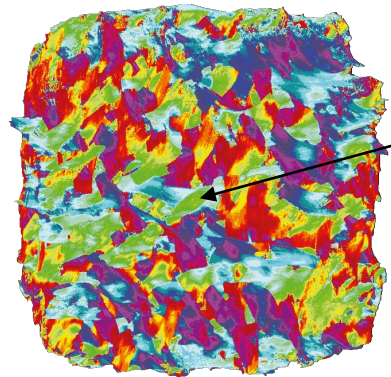
Process Simulation

Conclusions

Question: How well does the Folgar-Tucker model describe the fiber orientation behavior of C-SMCs?

Main differences between polarization camera image and simulation result:

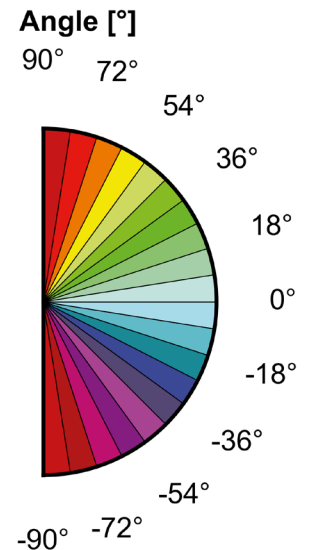
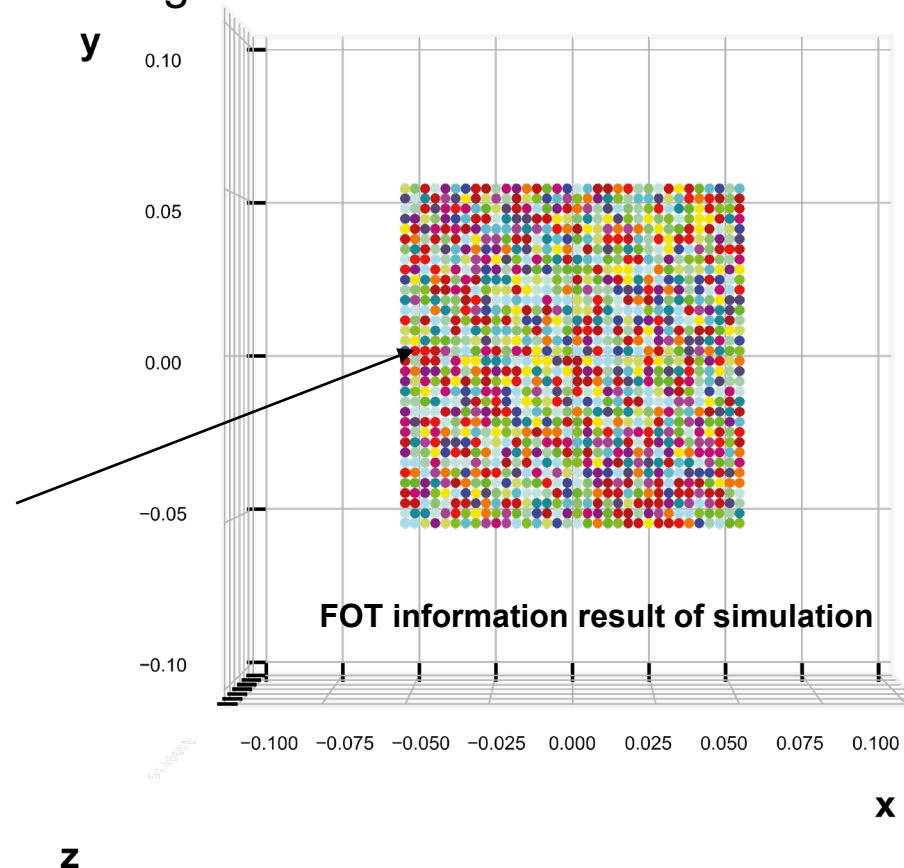
→ Short Shot with tool gap of 8 mm:



Polarization camera image

Long fiber reinforcement
formed by yarn cuttings
⇒ Grid cells in analyses
are connected
⇒ FOT in grid cells are
influenced **by** each other

Every element in simulation
model describes one fiber
distribution (FOT)
⇒ Elements in simulation **are**
not directly connected
⇒ FOT in elements **are not**
influencing each other



Introduction

Motivation

Material & Process
Characterization

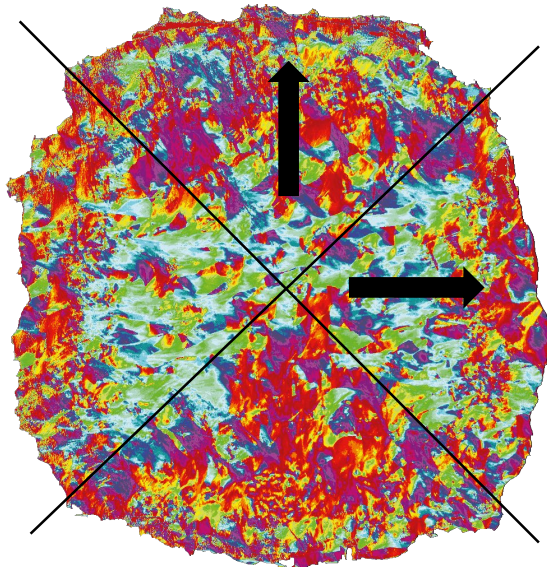
Process Simulation

Conclusions

Question: How well does the Folgar-Tucker model describe the fiber orientation behavior of C-SMCs?

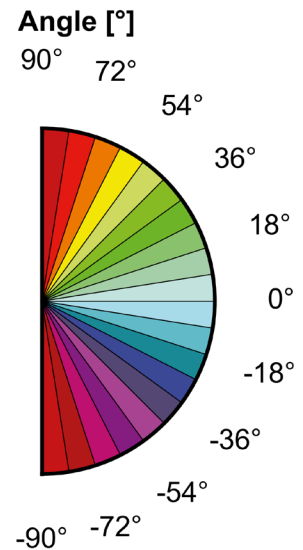
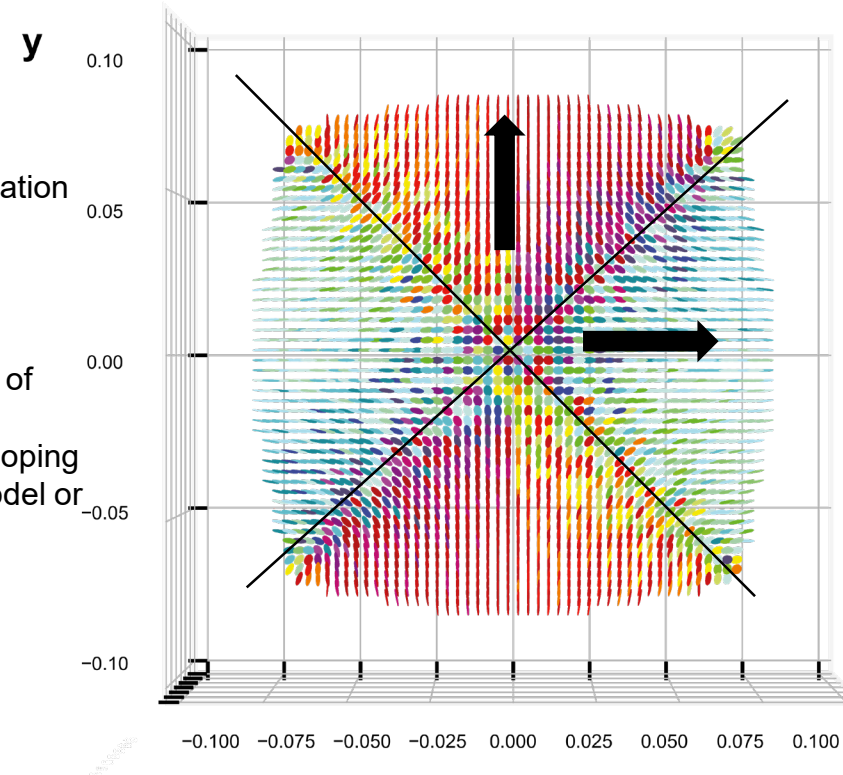
Is the tendency correct?

→ Short Shot with tool gap of 3 mm:



Polarization camera image

Same orientation tendency in simulation
But: Stronger orientation behavior
Reason: No resistance against movement caused by neighboring elements
Can be influenced by: Calibration of material parameter
Can be optimized by: Using/developing a more suitable fiber orientation model or fiber interaction model



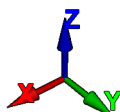
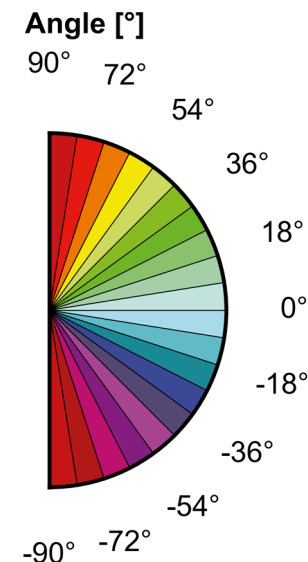
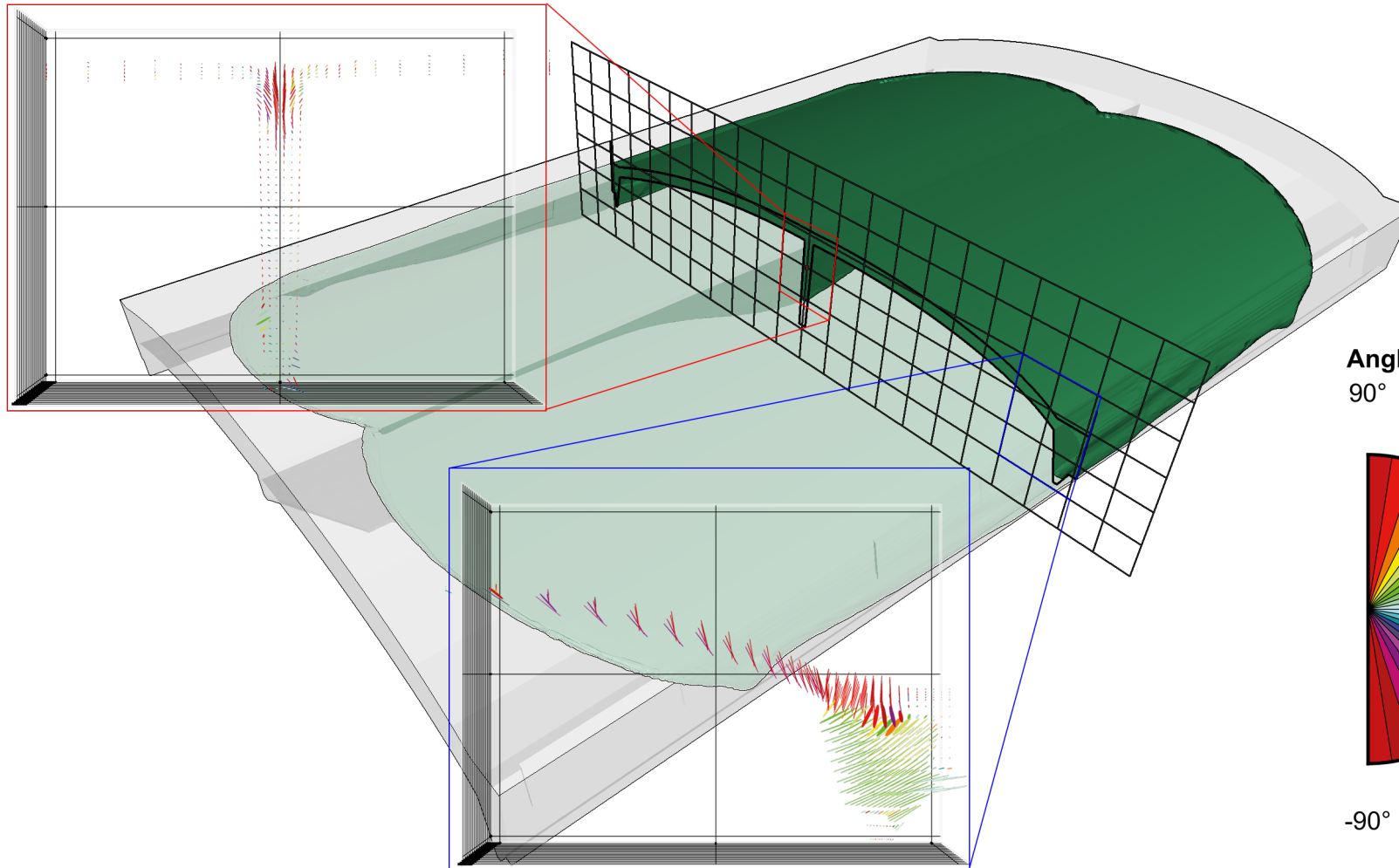
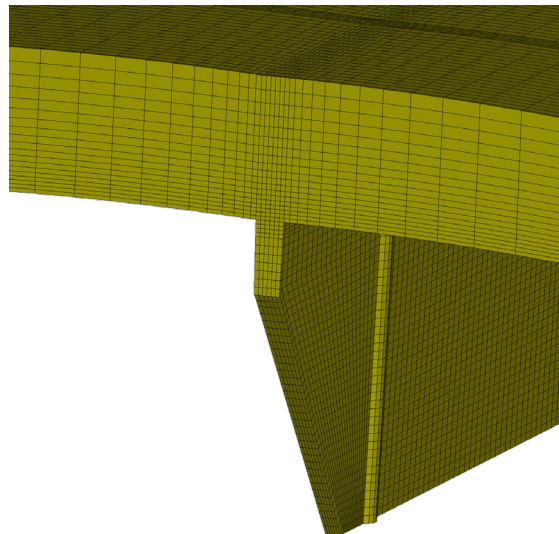
Introduction

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Introduction

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Several innovative methods have been developed for the material and process characterization of C-SMC materials focusing on fiber orientation and flow behavior.

- Fiber orientation: Semi-finished product (Polarization imaging)
- Flow/filling characterization (Press rheometry constant area and constant mass)
- Fiber orientation: Pressed specimens (Polarization imaging)

A non-linear elastic piecewise plastic material model with fiber orientation back-coupling based on the Folgar-Tucker-Model + Maier-Saupe term has been implemented in LS-DYNA as a user-defined material model.

- Initial qualitative validations show great results!

This project has been carried out in close collaboration with the Flow and Material Simulation Department of the Fraunhofer Institute for Industrial Mathematics (ITWM) within the framework of the High Performance Center Simulation and Software Based Innovation.



HIGH PERFORMANCE CENTER
SIMULATION- AND
SOFTWARE-BASED
INNOVATION



The polarization hardware used within this project has been developed with the help of the Electronic Imaging Department of the Fraunhofer Institute for Integrated Circuits (IIS).



Thank you for your attention!

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Composite Aneurysm Clip